# Multimodal Autonomous Al Agents

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# Large Language Models

In-context learning

Zero-shot abilities

Sensitive to word orderings

LLM

Strong text representations

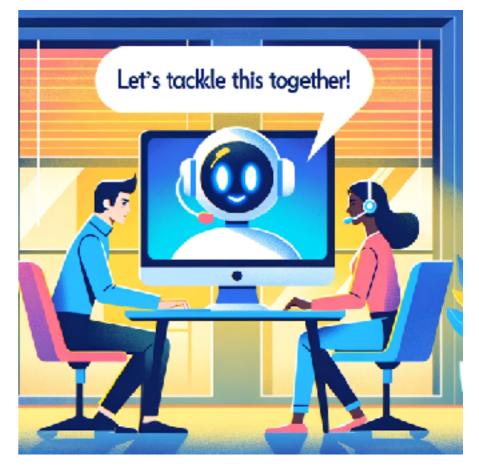
(Greater) sensitivity to input prompts

World knowledge

Generate long and coherent text

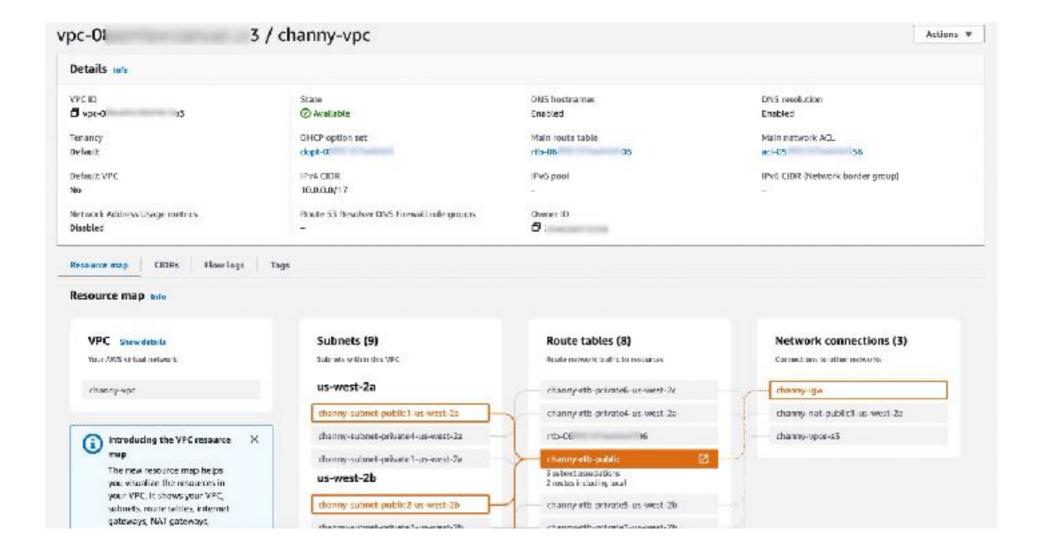
## **Autonomous Al Agents**

- Many productive tasks we perform today are done on the computer
  - And many of these are on the web
- Many opportunities to automate menial tasks
- Augment human capabilities

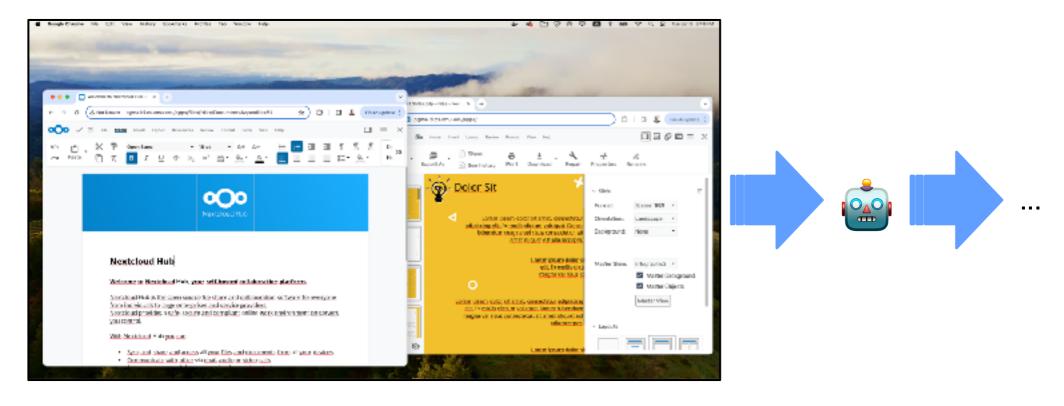


Generated with DALLE

## **Autonomous Agents**

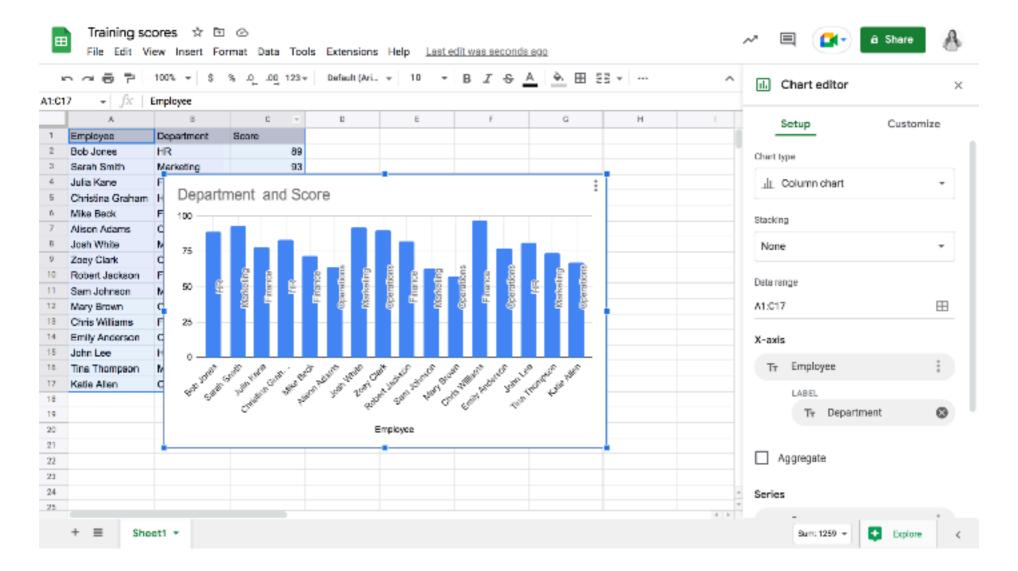


# **Autonomous Agents**



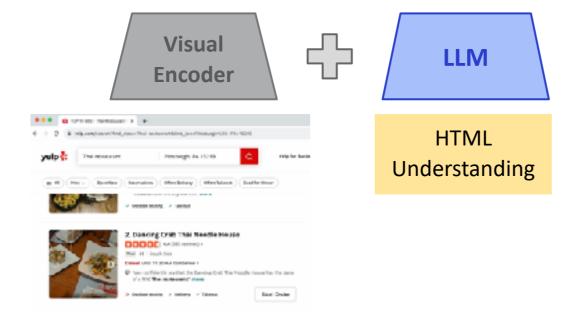
**Task:** "Create a set of PowerPoint slides to present the content in this paper."

# **Autonomous Agents**



# Web Agents

Web Grounding



# Web Agents

#### Web

Shunyu Yao, REACT Synergizing Reasoning and Acting in Language Models, 2023

Jason Wei et al, Chain of Thought Prompting Elicits Reasoning in Large Language Models, 2022

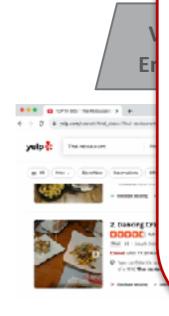
Reiichiro Nakano et al, WebGPT: Browser-assisted Question-Answering with Human Feedback, 2021.

Xiang Deng et al, MIND2WEB: Towards a Generalist Agent for the Web, 2023

Timo Schick et al, Toolformer: Language Models can Teach Themselves to Use Tools, 2023

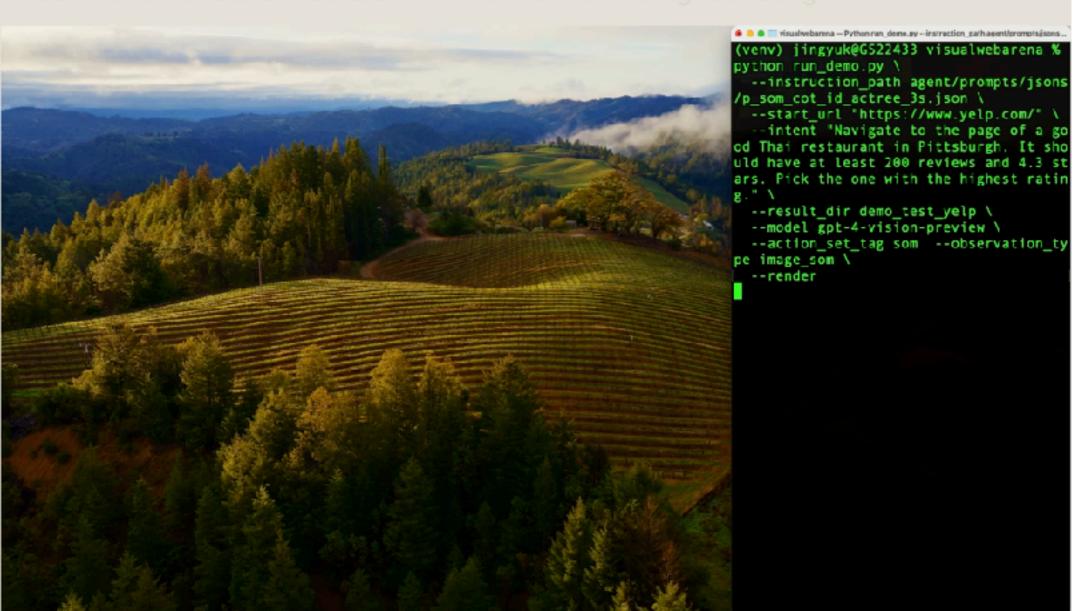
Shibo Hao et al, ToolkenGPT: Augmenting Frozen Language Models with Massive Tools via Tool Embeddings, 2023

Yang et al., SWE-agent: Agent-Computer Interfaces Enable Automated Software Engineering, 2024

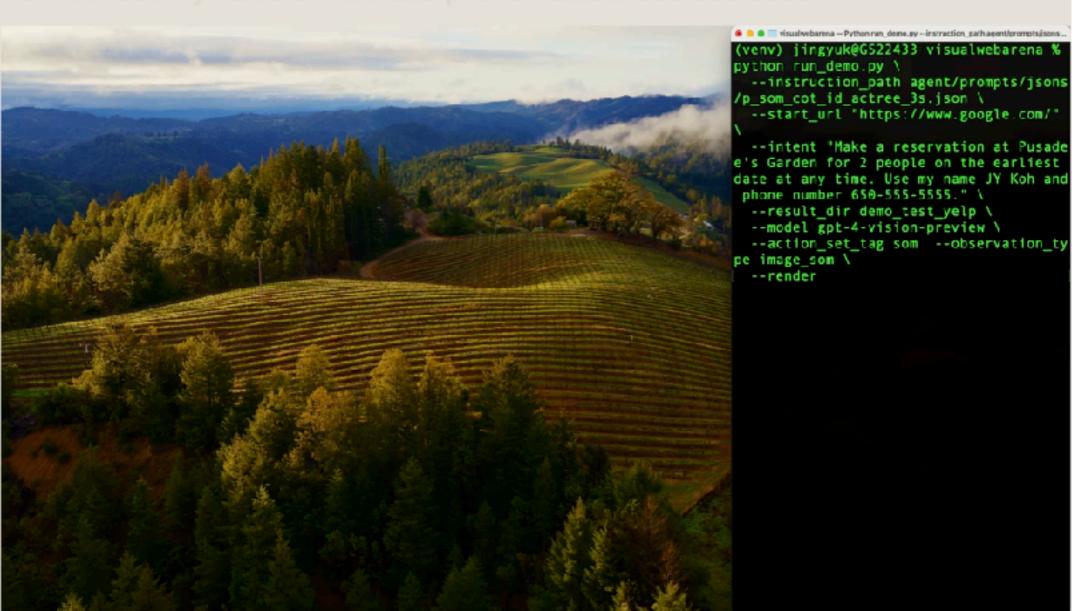


Task: Navigate to a page of a good Thai restaurant in Pittsburgh. It should have at least 200 reviews and 4.3 stars. Pick the one with the highest rating

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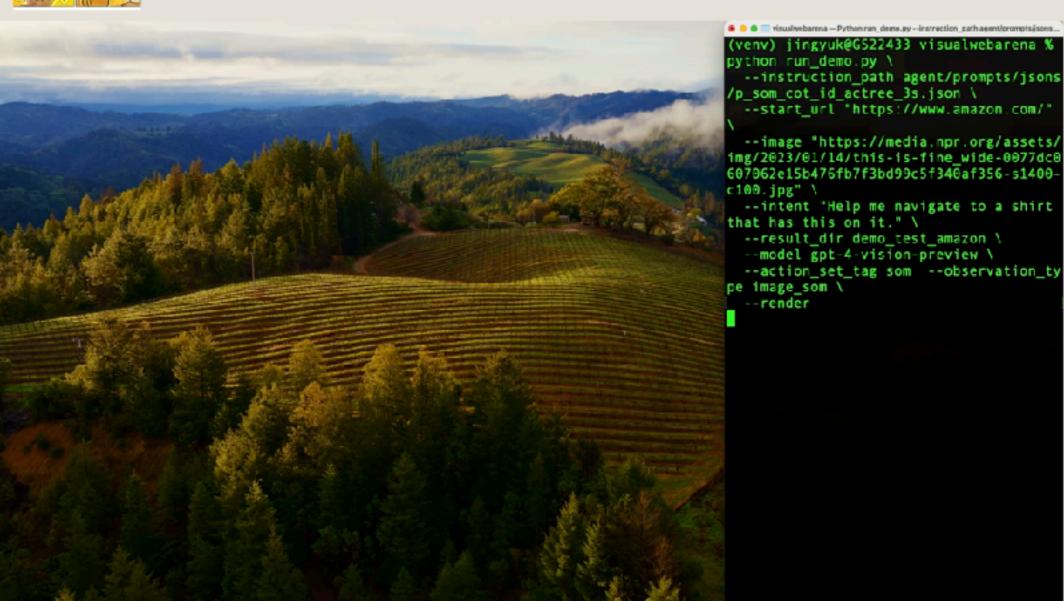


Task: Make a reservation at Pusadee's Garden for 2 people on the earliest date for distance. Use my name JY Koh and phone number 650-555-5555.





#### Task: Help me navigate to a shirt that has this on it.



#### Talk Outline

- VisualWebArena -- Evaluating Multimodal Agents on Realistic Visual Web Tasks (Koh et al., ACL 2024)
- Tree Search for Language Model Agents (Koh, McAleer, Fried, Salakhutdinov, arXiv 2024)
- Towards Internet-Scale Training For Agents (Trabucco, Sigurdsson, Piramuthu, Salakhutdinov, arXiv 2025)

#### WebArena

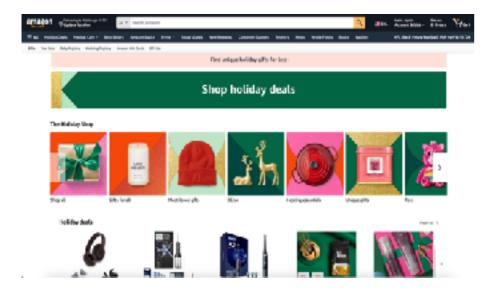


Shuyan Zhou

Frank Xu

- Most realistic web environment at the moment
- Websites from popular categories (shopping, Reddit, GitLab)
  - Self-hosted open source re-implementations
  - Data from real websites (Amazon, Reddit, GitHub)
- Tasks are easy for humans (78% success rate) but difficult for language model agents (14%)
- But: Tasks are designed to use just text and HTML source code
- Messy HTML, JavaScript: usually minified or compressed for efficiency
- Interactive elements don't display correctly in HTML
  - e.g., JavaScript/CSS code that moves objects after the page is loaded
- Context length: HTML pages are complex, easily filling up > 100k tokens

#### HTML is insufficient



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  - e.g., JavaScript/CSS code that moves objects after the page is loaded
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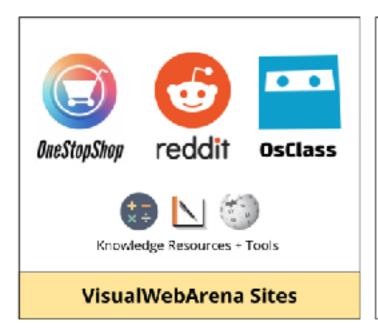
#### VisualWebArena

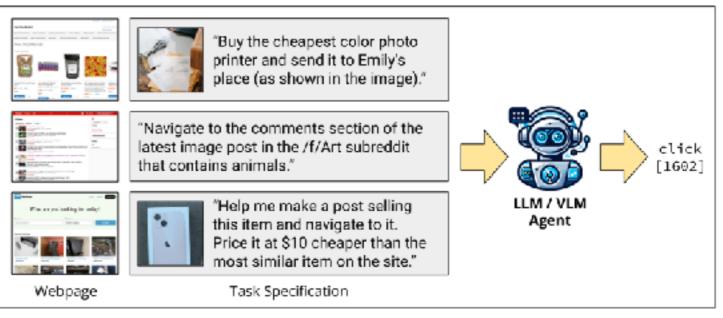


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ın Zhou 🔋 Frank Xu

- Build and track the progress of multimodal agents
- We design visually grounded tasks to test these abilities
- Visual inputs (and outputs) allow for unique, interesting, and realistic tasks

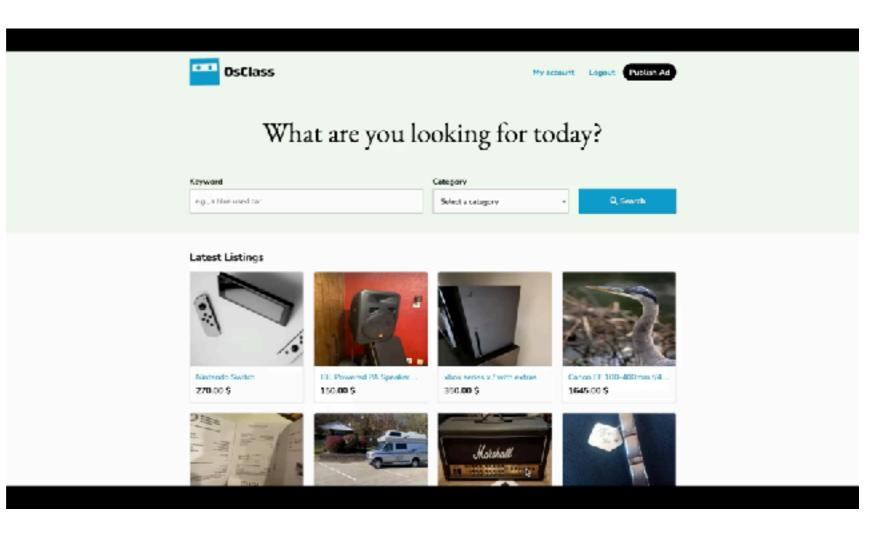




### VisualWebArena: Classifields

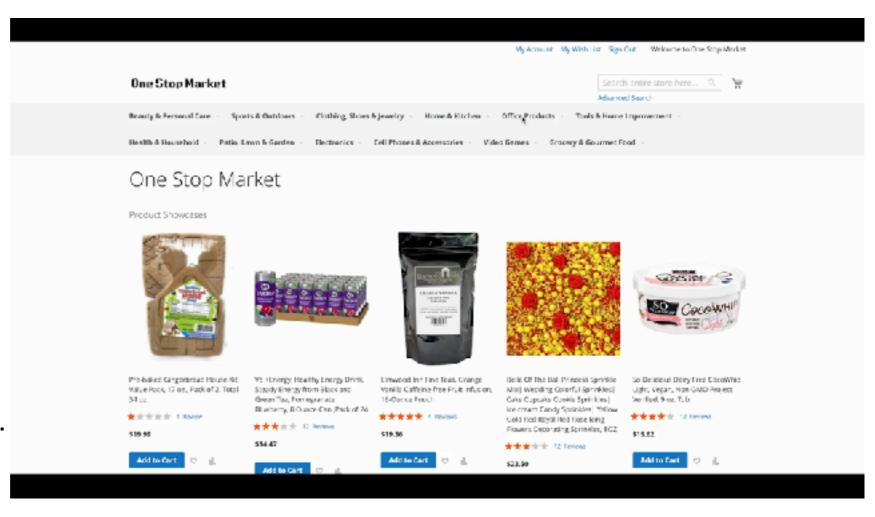


**Task:** Find this exact bike that's listed for \$300-500 and post a comment offering \$10 less than their asking price.



# VisualWebArena: Shopping

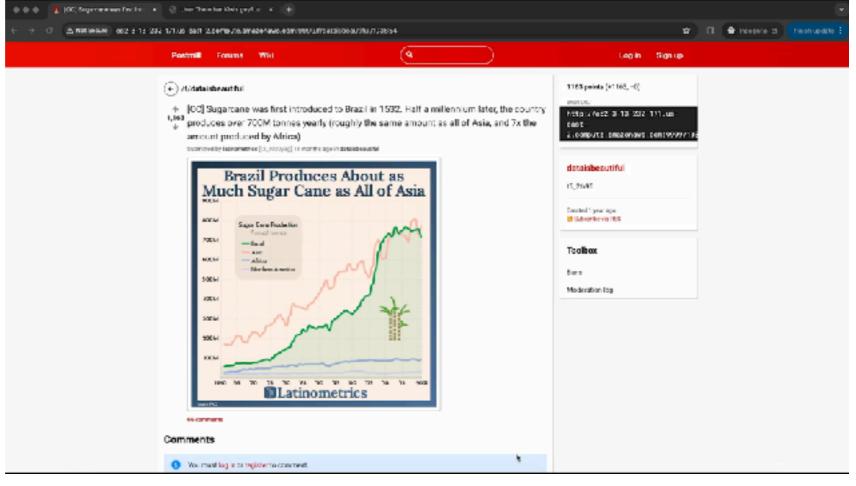




### VisualWebArena: Reddit



Task: What is the 2022 total nominal GDP of the area that produces most sugarcane in the year of 2021? (in billion)?



### VisualWebArena

POMDP environment:  $\mathcal{E} = \langle \mathcal{S}, \mathcal{A}, \mathcal{O}, \mathcal{T} \rangle$ ,

ullet Observations  ${\cal O}$ 



Actions A

Action Type a	Description
click [elem]	Click on element elem.
hover [elem]	Hover on element elem.
type [elem] [text]	Type text on element elem.
press [key_comb]	Press a key combination.
new_tab	Open a new tab.
tab_focus [index]	Focus on the i-th tab.
tab.close	Close current tab.
goto [url]	Open url.
go_back	Click the back button.
go_forward	Click the forward button.
scroll [up down]	Scroll up or down the page.
stop [answer]	End the task with an optional output.

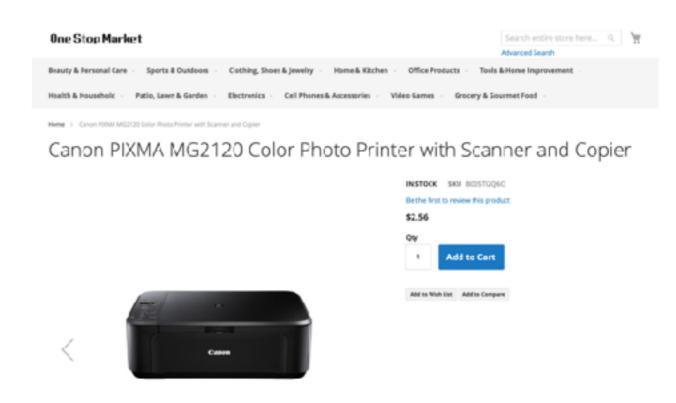
Deterministic transition function

$$\mathcal{T}: \mathcal{S} \times \mathcal{A} \longrightarrow \mathcal{S}$$

ullet Reward function:  $r(\mathbf{a},\mathbf{s})$ 

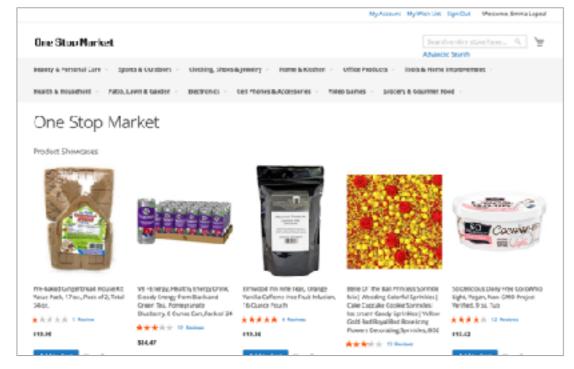
# Image Inputs:



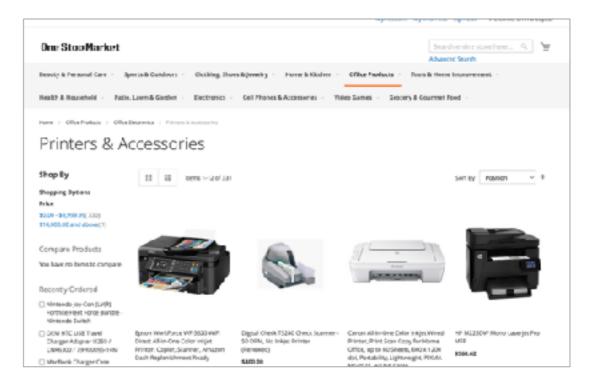


**Shopping** 



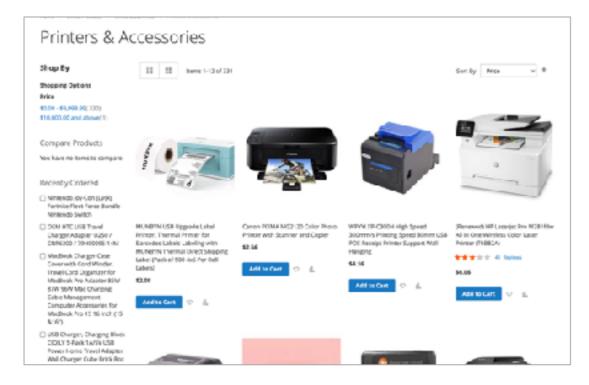


**Step 0:** Start on the homepage of OneStopMarket.

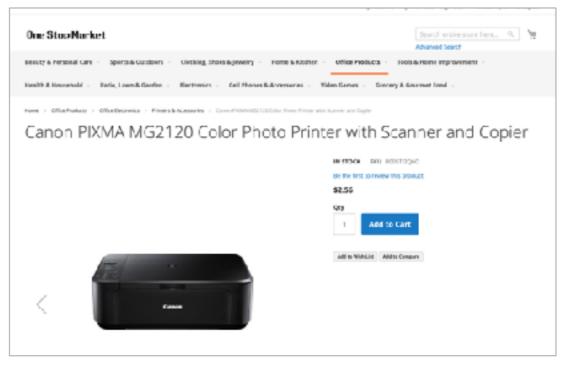


Step 1: Navigate to the printers category.



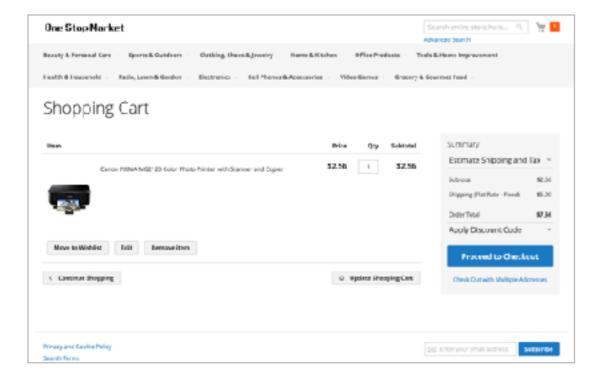


Step 2: Sort by descending price.



**Step 3:** Click on the cheapest color photo printer.



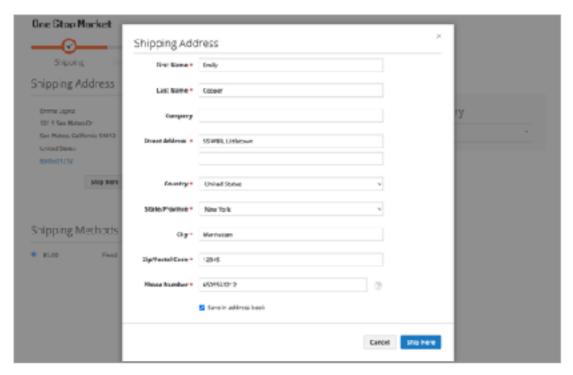


One Stoo Market Shipping Address Emme Lopez Order Summary 10133HF Males OV 1 Item in Cart United Status 8465006711 - New Address Shipping Methods 15.00 Flat Rate

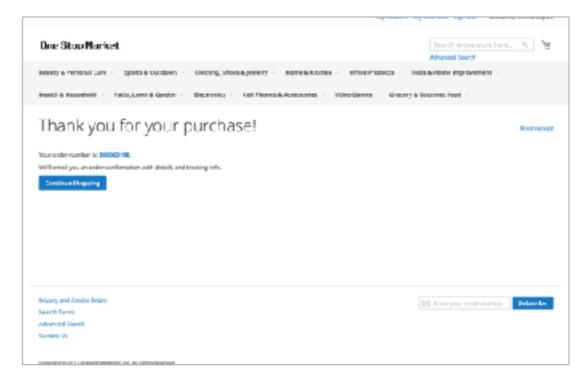
Step 4: Add it to the shopping cart.

Step 5: Proceed to checkout





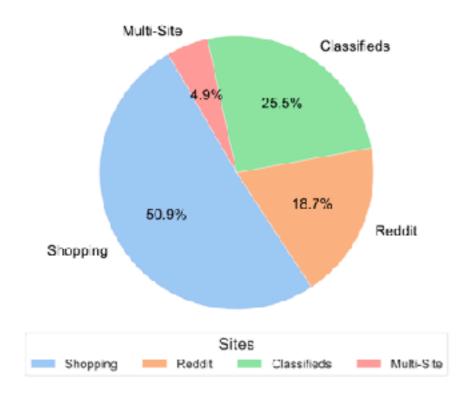
**Step 6:** Edit address to that of Emily's place.



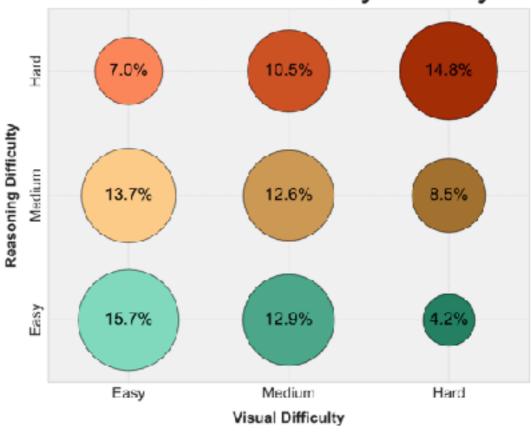
Step 7: Place the order

### VisualWebArena

#### Distribution of Tasks Across Sites



#### Distribution of Tasks by Difficulty



# **Execution Based Evaluation**

Webpage / Input Image(s)	Example Intent	Reward Function $r(s,a)$ Implementation	
The second of th	What is the ISIN of the company that occupies the largest portion in Warren Buffet's portfolio? Answer using the information from the Wikipedia site in the second tab.	exact_match(â, "US0378331005")	
	Add something like what the man is wearing to my wish list.	<pre>url="/wishlist" locator(".wishlist .product-image-photo") eval.vqa(s, "Is this a polo shirt? (yes/no)", "yes") eval.vqa(s, "Is this shirt green? (yes/no)", "yes")</pre>	
Lades File	Create a post for each of the fol- lowing images in the most related forums.	$eval\_fuzzy\_image\_match(s, a^*)$	
Printing 28.2.1 Topots 86 - Lave Miles, Fartury Westury While, Fartury Westury Waster Street Waster	Navigate to my listing of the white car and change the price to \$25000. Update the price in the description as well.	url="/index.php?page=item&id=84144" must_include(â, "\$25000  OR  \$25,000") must_exclude(â, "\$30000  OR  \$30,000")	

# LLM and VLM Agents

# Visual Language Models as Agents

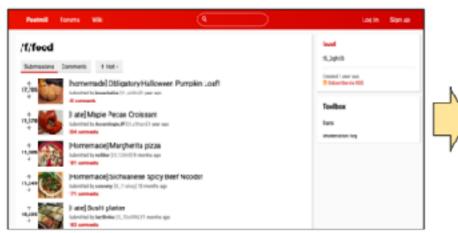
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                          link 'Image'
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Accessibility tree / HTML representations: Cluttered with unnecessary information, long and confusing context.

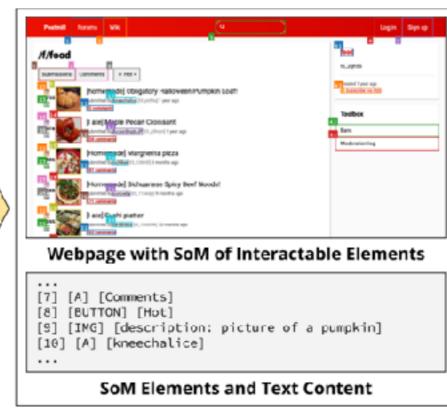


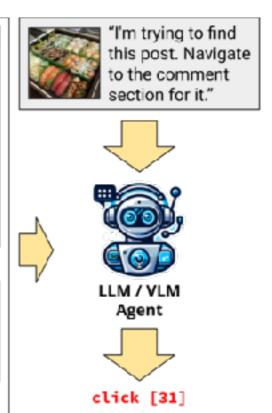
**VLM + SoM:** Simplified representation with <u>Set-of-Marks (SoM)</u> prompting over interactable elements.

# Visual Language Models as Agents

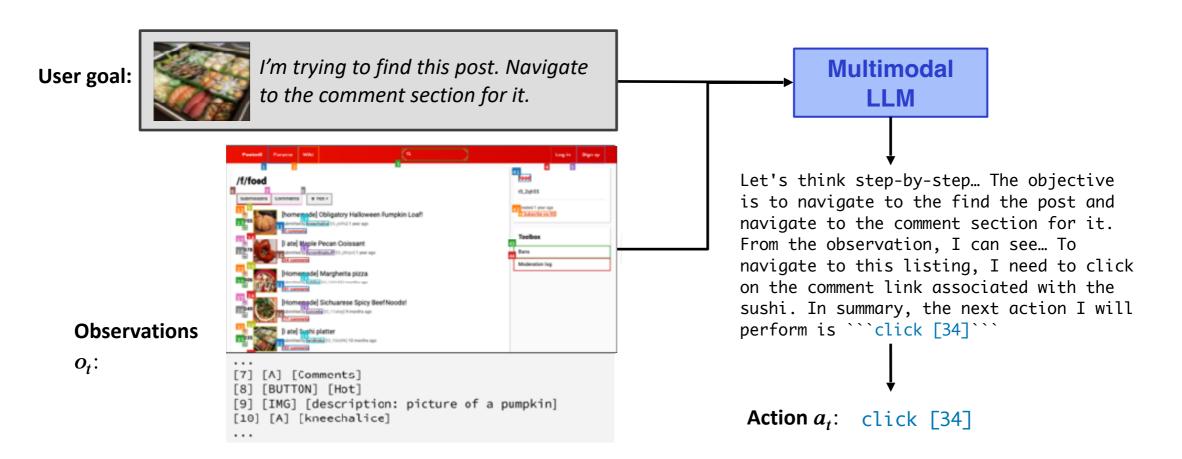


**Original Webpage** 



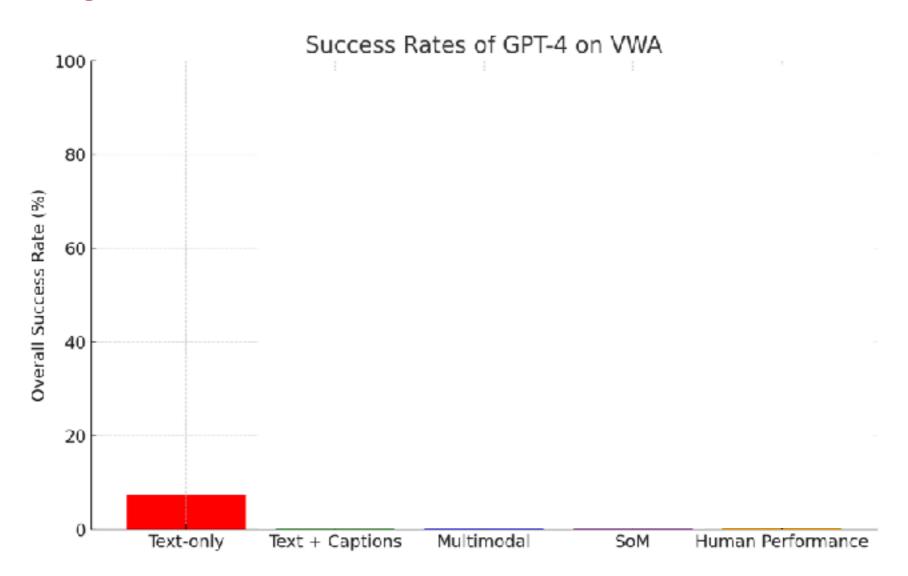


# Visual Language Models as Agents



**VLM + SoM:** Simplified representation with <u>Set-of-Marks (SoM)</u> prompting over interactable elements.

# **Baseline Agents**

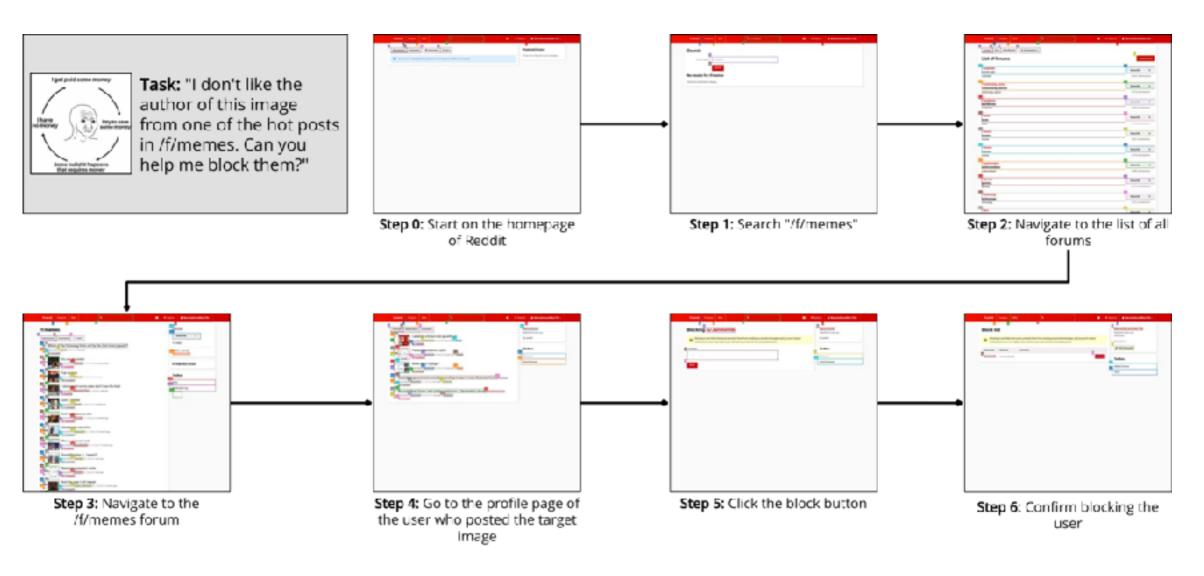


# Baseline Agents: Text-based LLMs

Model Type	LLM Backbone	Visual Backbone	Inputs	Success Rate (†)
Text-only	LLaMA-2-70B	-	Access bility Tree	1.10%
	Mixtral-8x7B			1.76%
	Gemini-Pro			2.20%
	GPT-3.5			2.20%
	GPT-4			7.25%
Caption-augmented	LLaMA-2-70B	BLIP-2-T5XL	Accessibility Tree + Captions	0.66%
	Mixtral-8x7B	BLIP-2-T5XL		1.87%
	GPT-3.5	LLaVA-7B		2.75%
	GPT-3.5	BLIP-2-T5XL		2.97%
	Gemini-Pro	BLIP-2-T5XL		3.85%
	GPT-4	BLIP-2-T5XL		12.75%

# Baseline Agents: Multimodal LLMs

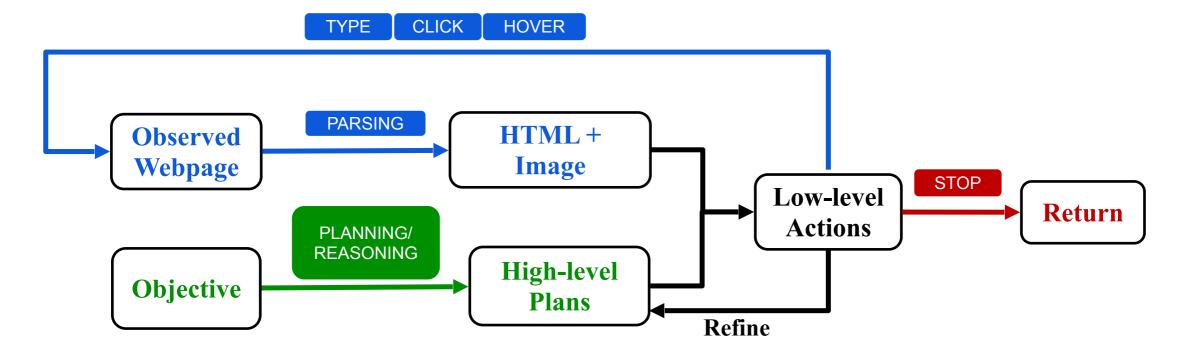
Model Type	Multimodal Model	Inputs	Success Rate (1)
Multimodal	IDEFICS-80B-Instruct	Image + Captions + Accessibility Tree	0.77%
	CogVLM		0.33%
	Gemini-Pro		6.04%
	GPT-4V		15.05%
Multimodal (SoM)	IDEFICS-80B-Instruct	Image + Captions + SoM	0.99%
	CogVLM		0.33%
	Gemini-Pro		5.71%
	GPT-4V		16.37%
Human Performance	-	Webpage	88.70%



Successful execution trajectory of the GPT-4V + SoM agent on the task for blocking a user that posted a certain picture

## Web Agent Architecture

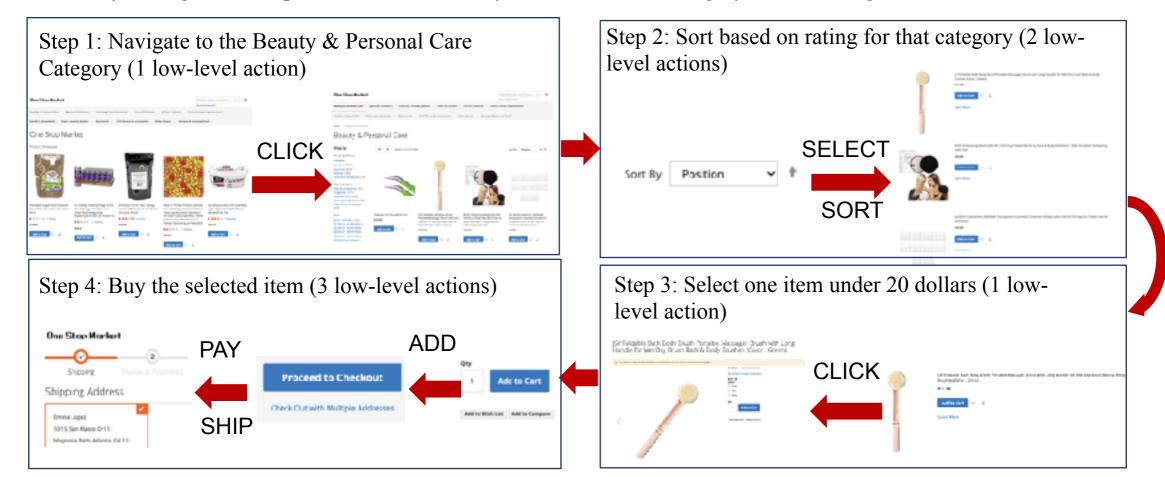
- Model architecture of our interactive agent:
  - High-level Planning and Reasoning
  - Observation Parsing
  - Low-level Action Generation



## **Planning**

### High-level plans are important for long-sequence and complex objectives.

Task: Buy the highest rated product from the Beauty & Personal Care category within a budget under 20.

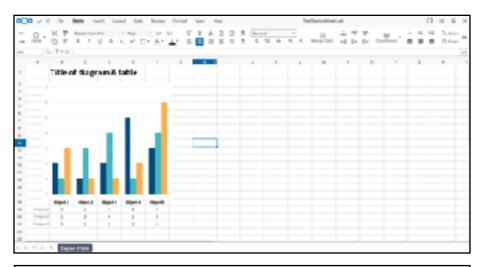


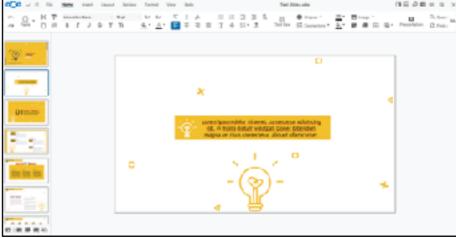
### **Measuring Productive Tasks**

VisualWebArena is a step towards building general purpose agents. But:

- Tasks are not very consequential: do not represent significant economic value
- Tasks are simpler, as current LLM agents do not even do well on these problems

**Long term:** Automate productive, economically valuable tasks





Examples from Collabora Online / LibreOffice.

### Common Failure Modes

- Long horizon reasoning and planning:
  - Models oscillate between two webpages, or get stuck in a loop
  - Correctly performing tasks but undoing them
  - Agents tend to stop exploration / execution too early

## What is Missing?

- We need to do a lot more to close the gap:
  - Reasoning and Planning over long horizons
  - Allow agent to Search, execute and coordinate multiple instances in parallel and ask for clarifications/confirmations
  - Strong vision-language-code models
  - Identifying the appropriate level of abstraction for agents (HTML/screenshots/ APIs)
- Multimodal models: Many real-world tasks require visual grounding to effectively solve (e.g., every task involving PowerPoint, Excel, Photoshop). To develop strong general agents, we will need to train and build strong visionlanguage models.

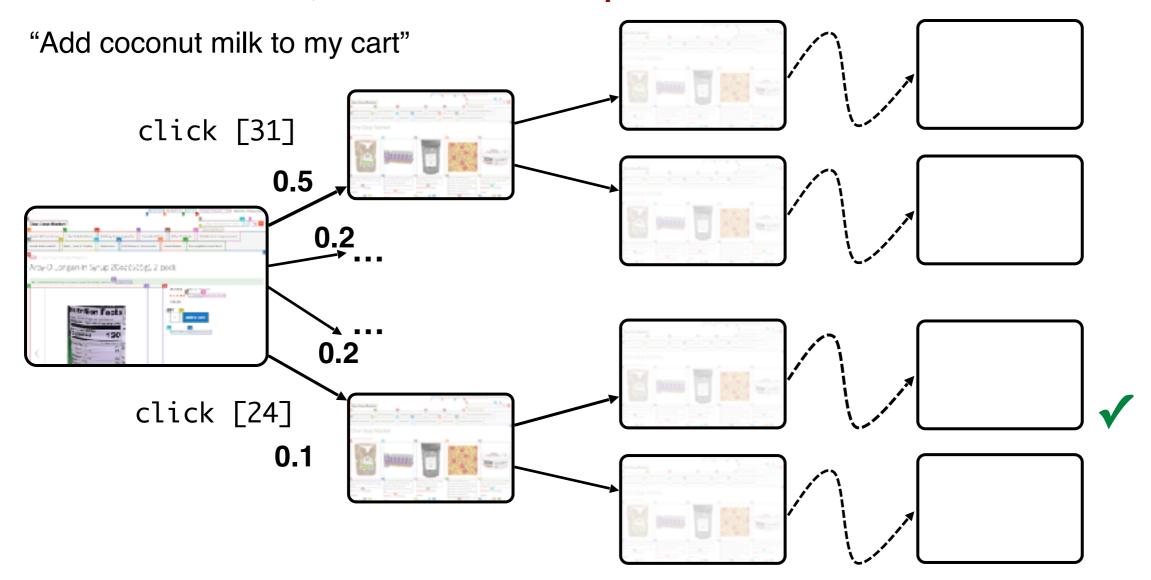
### Talk Outline

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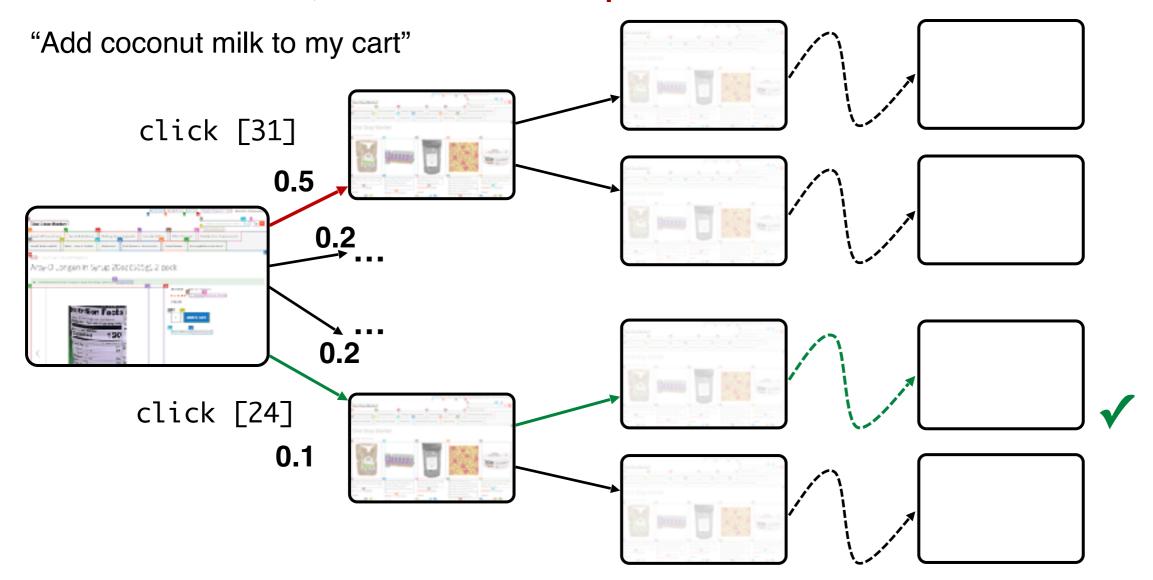
# **Exponential Error Compounding in Agents**

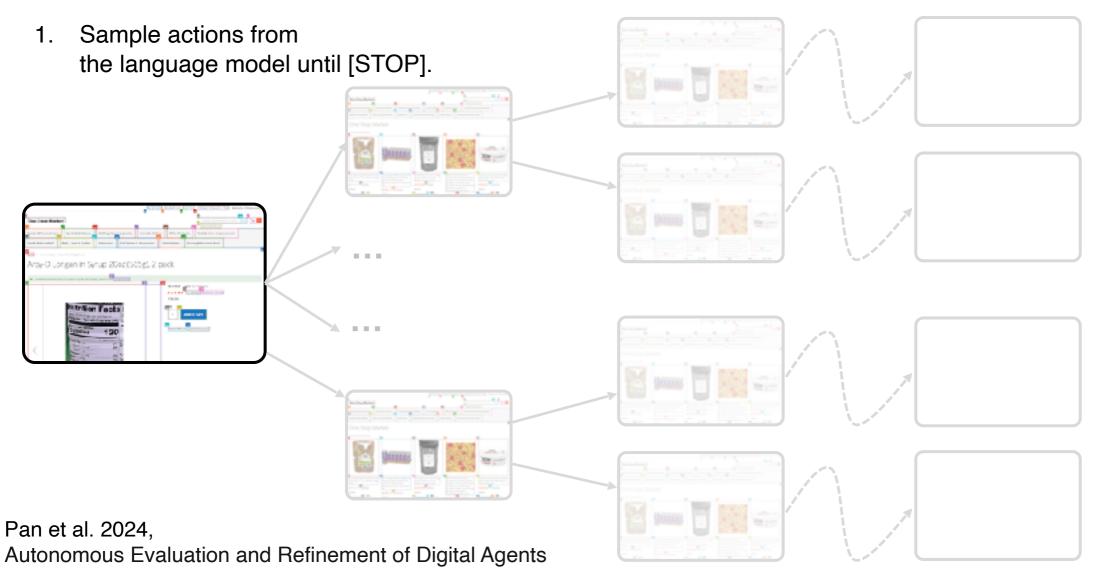
Accuracy @ k steps:						
1 (single step)	5	10	30	50		
90%	59.05%	34.87%	4.24%	0.52%		
95%	77.38%	59.87%	21.46%	7.69%		
99%	95.10%	90.44%	73.97%	60.50%		
99.9%	99.50%	99.00%	97.04%	95.12%		
99.99%	99.95%	99.90%	99.70%	99.50%		

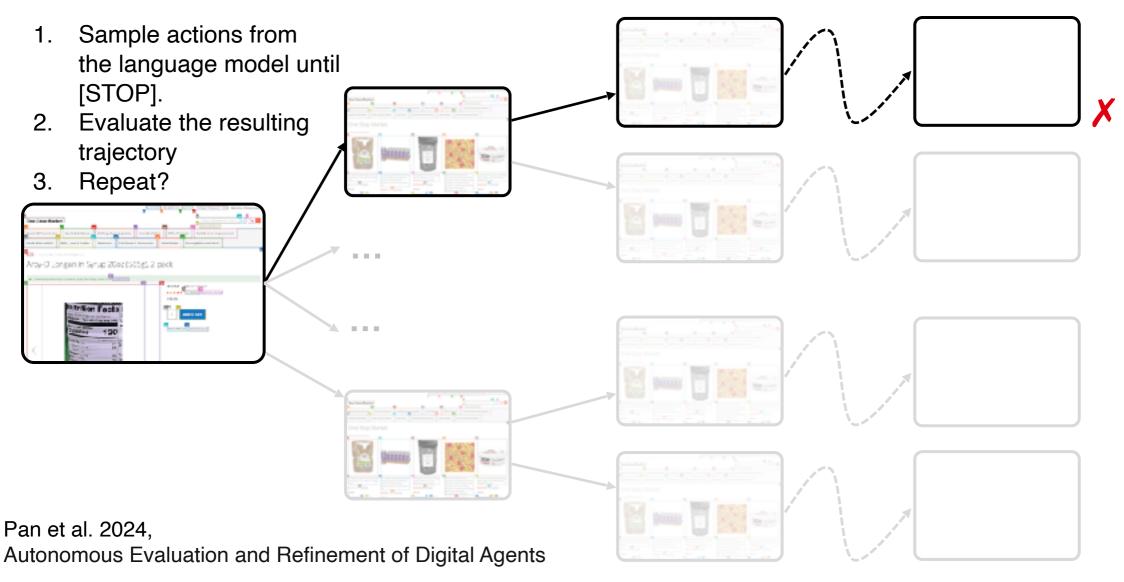
## Local Decisions; Global Consequences

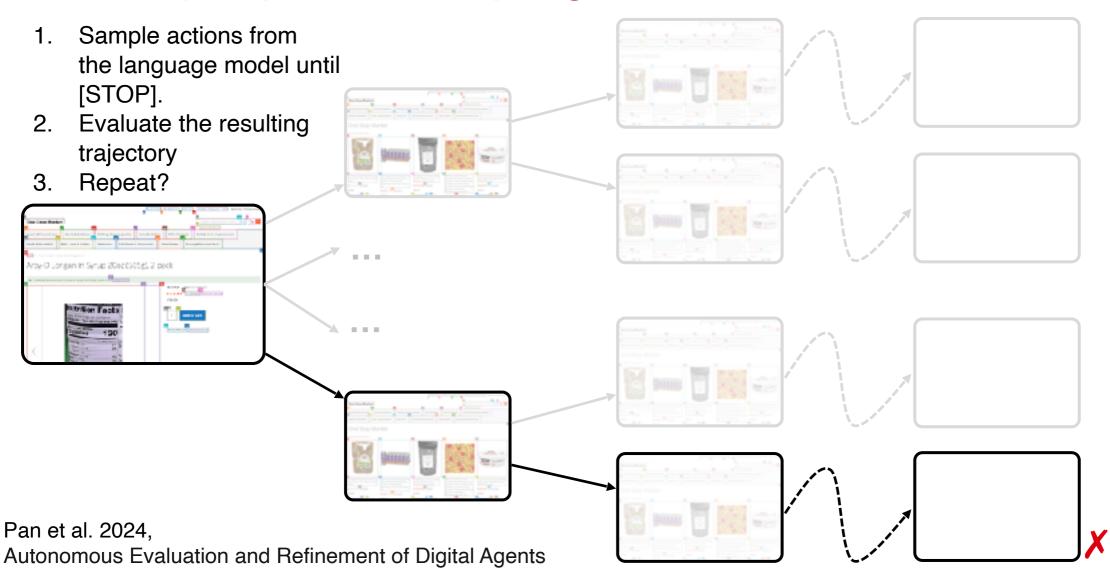


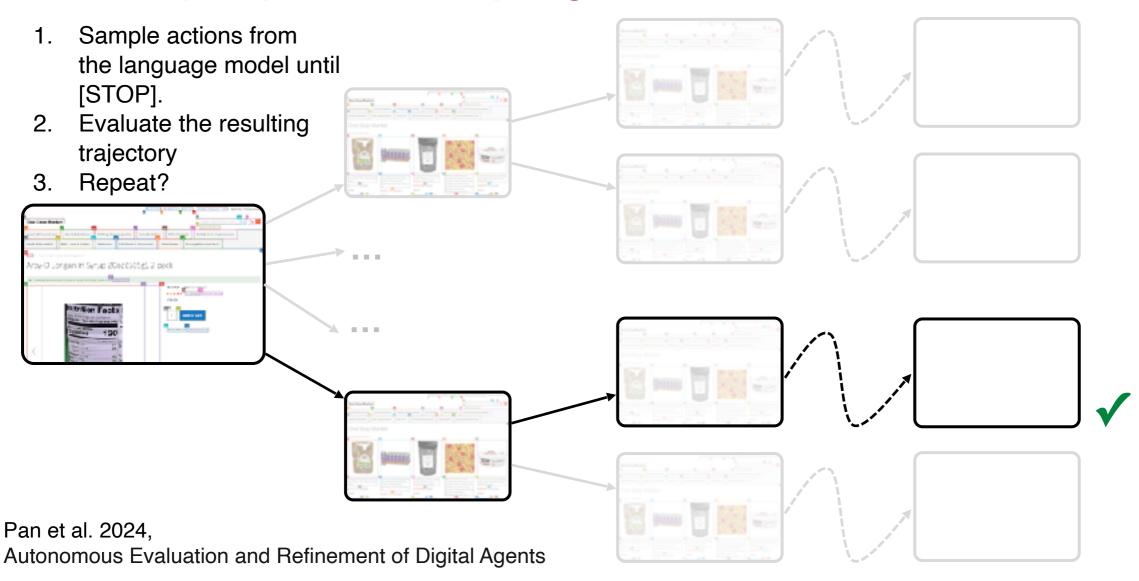
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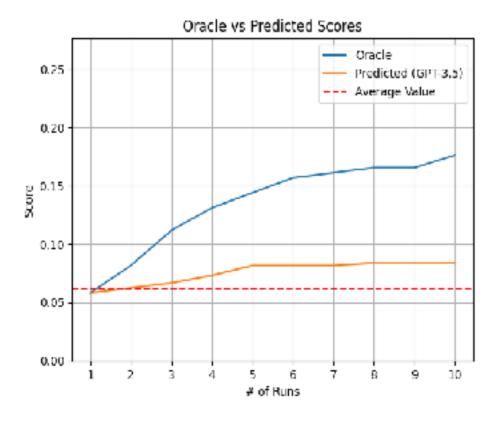












Repeated sampling helps!

- But the space is exponentially large. Can we guide exploration?
- Key idea: apply value function to intermediate nodes.

### Our Method: Tree Search

Koh

- Best-first search algorithm
- Ingredients:
  - Baseline agent to propose actions.
  - Way to backtrack in the environment.
  - A value function  $v_p = f_v(I, \{o_1, \dots, o_p\})$  to score and rerank candidate states.

v = 0.35

North Jorgan High, was Colled 2 pock

North Jorgan High, was Colled 2 pock

V = 0.55

In this work, we prompt a multimodal LLM (GPT-40) to act as an evaluator.



#### Legend

1 Step sequence

v = 1.0

State values

→ Backtracking

#### **GPT-40 Agent**





Starting State



#### Legend

1 Step sequence

v = 1.0

State values

→ Backtracking

#### **GPT-40 Agent**









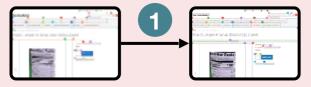
1 Step sequence

v = 1.0

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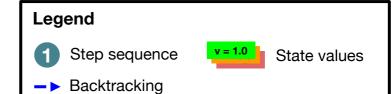
#### **GPT-40 Agent**





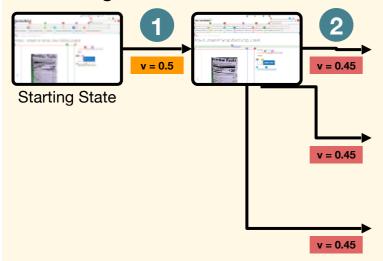
Starting State





#### **GPT-40 Agent**







#### Legend

1 Step sequence

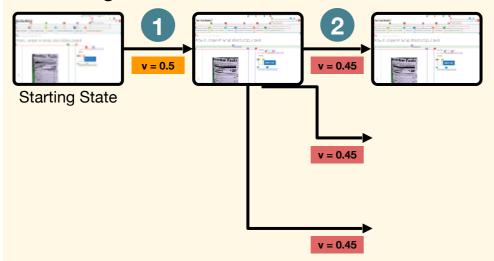
v = 1.0

State values

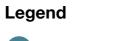
→ Backtracking

#### **GPT-40 Agent**









1 Step sequence

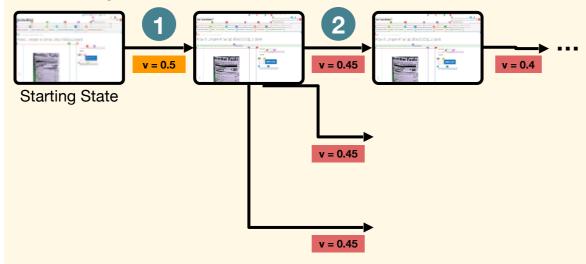
v = 1.0

State values

→ Backtracking

#### **GPT-40 Agent**







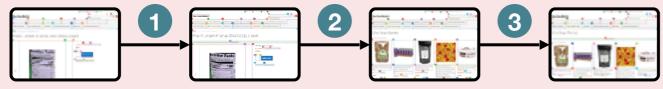
#### Legend

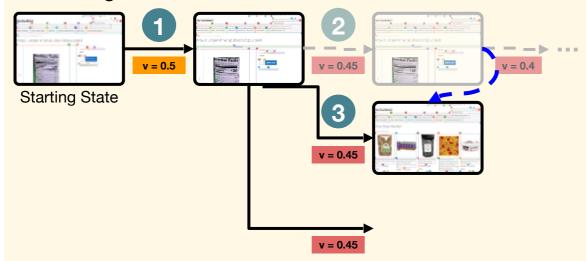
- 1 Step sequence
- v = 1.0

State values

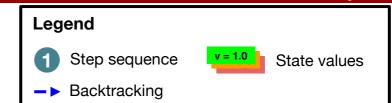
→ Backtracking

#### **GPT-40 Agent**



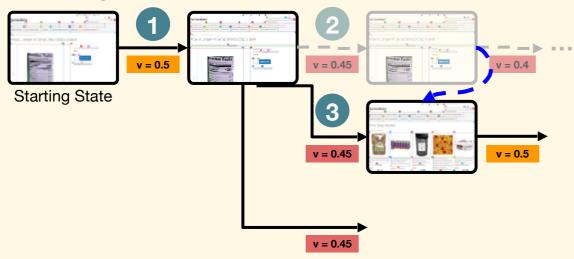
















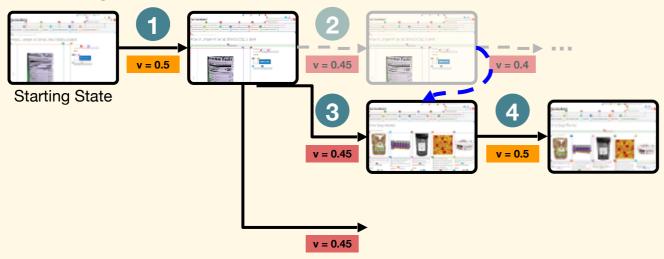
- 1 Step sequence
- v = 1.0

State values

→ Backtracking

#### **GPT-40 Agent**



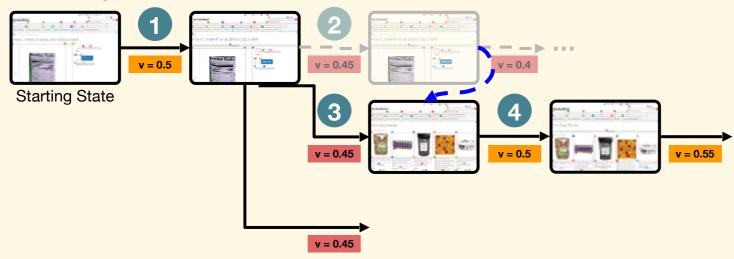






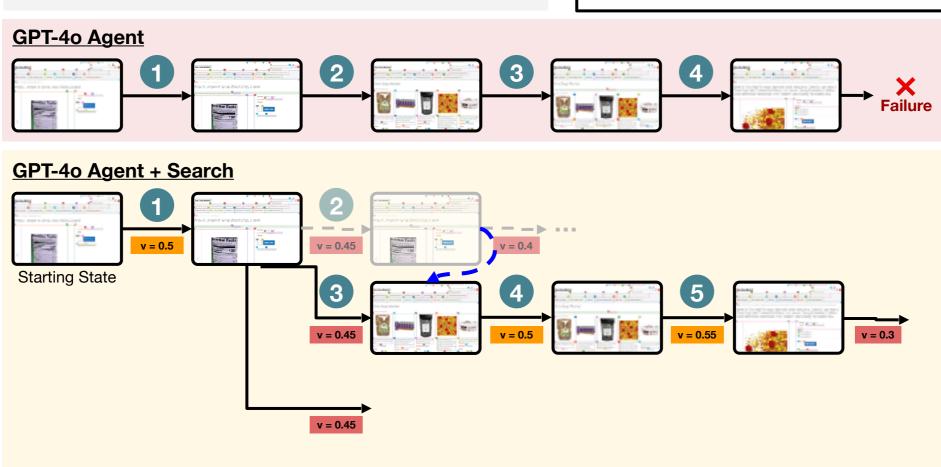




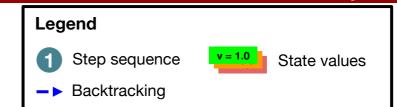










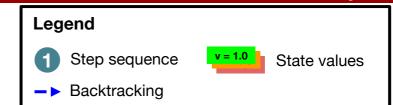


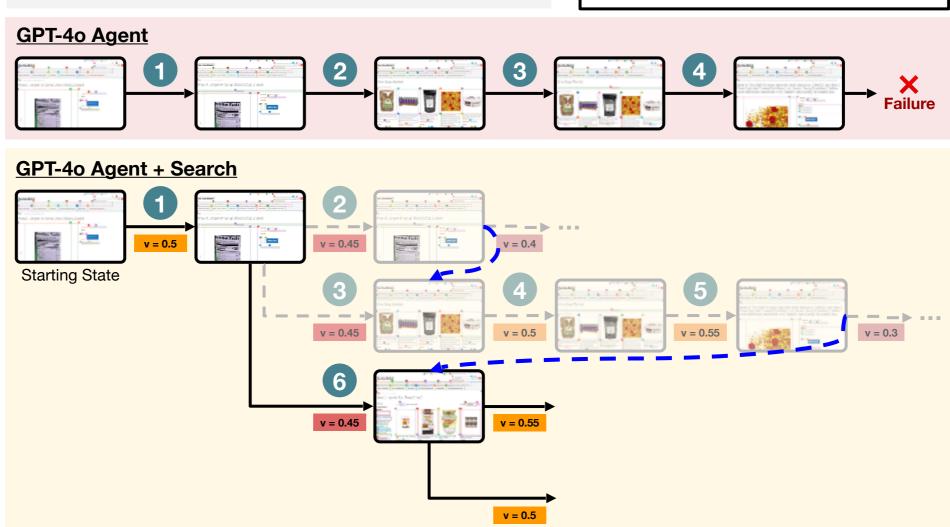




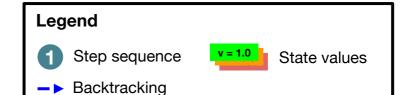


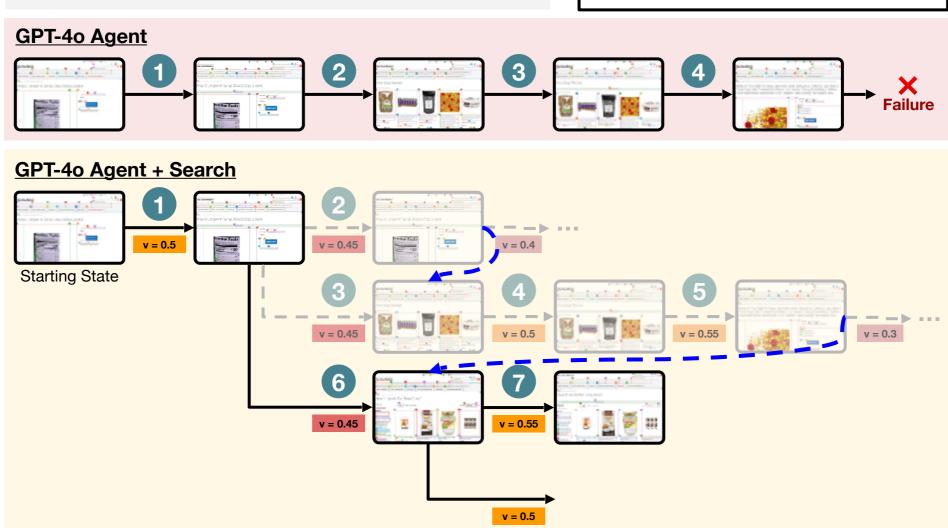




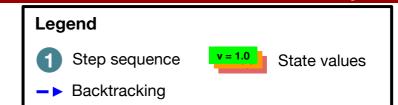


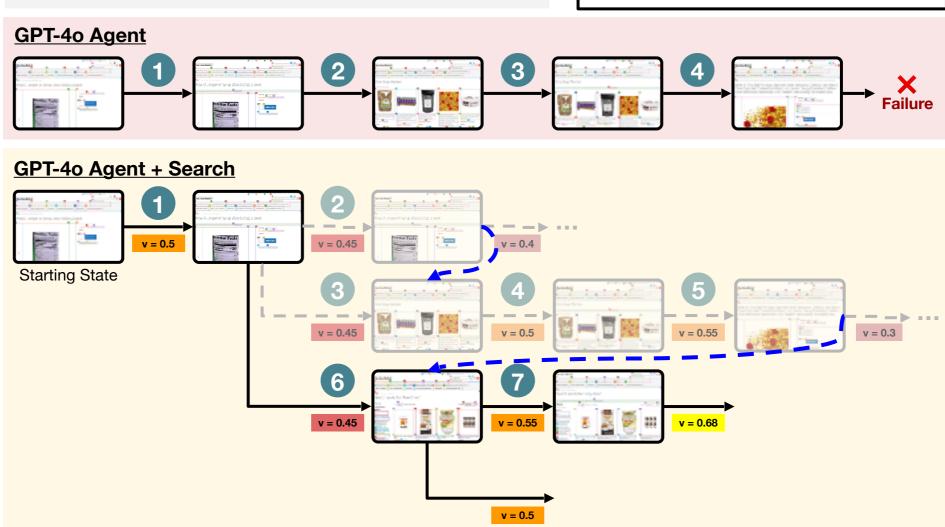






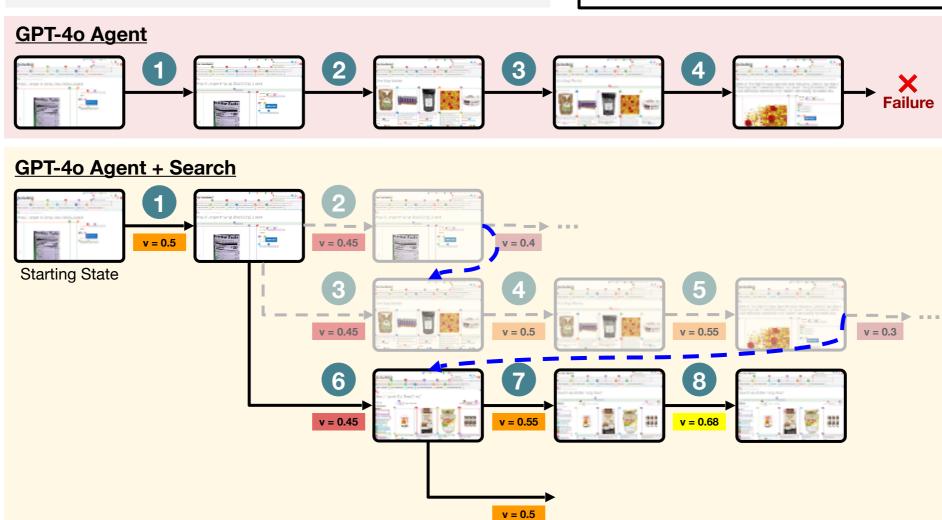




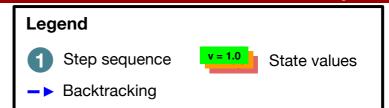


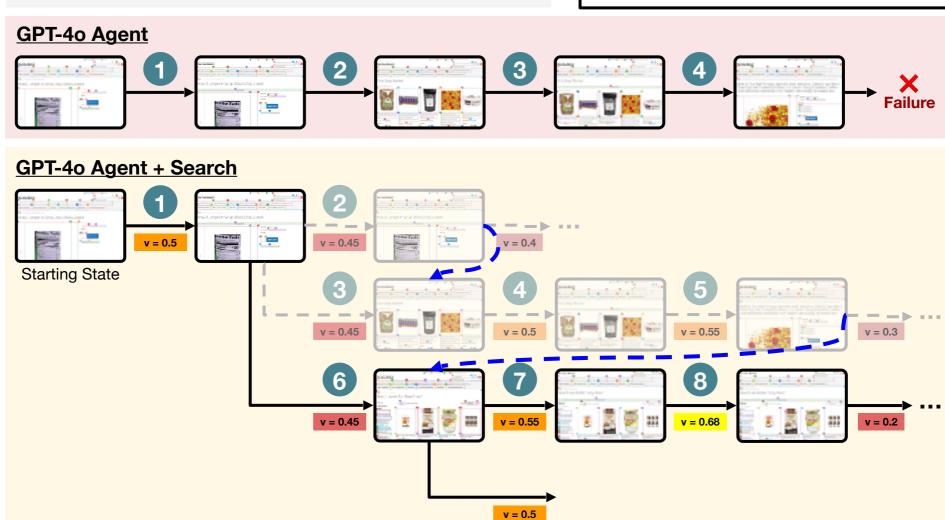




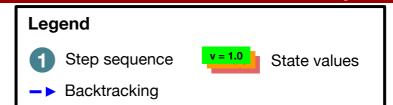


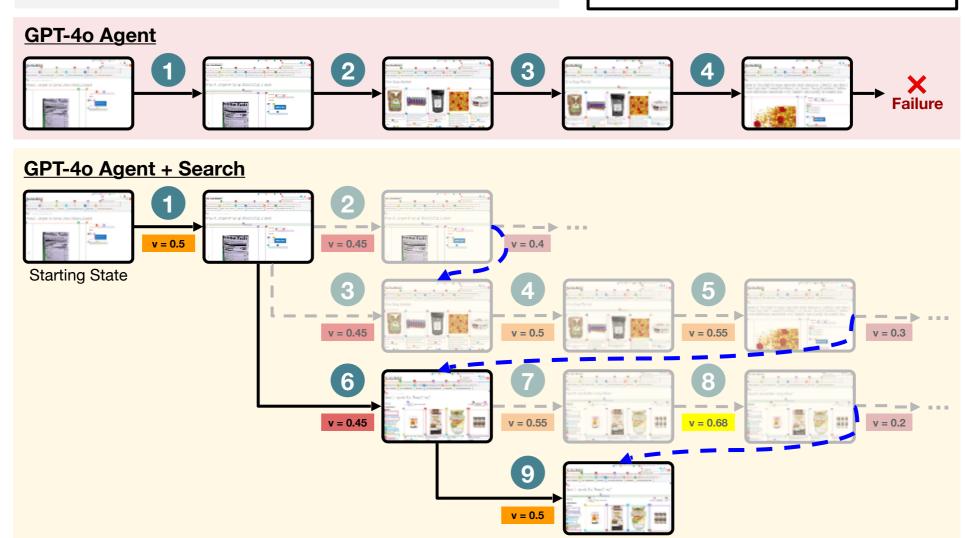






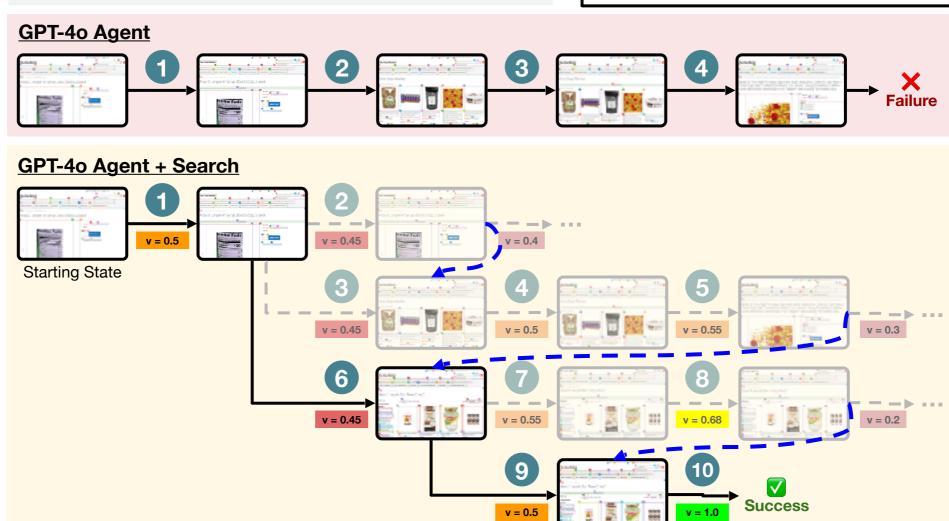




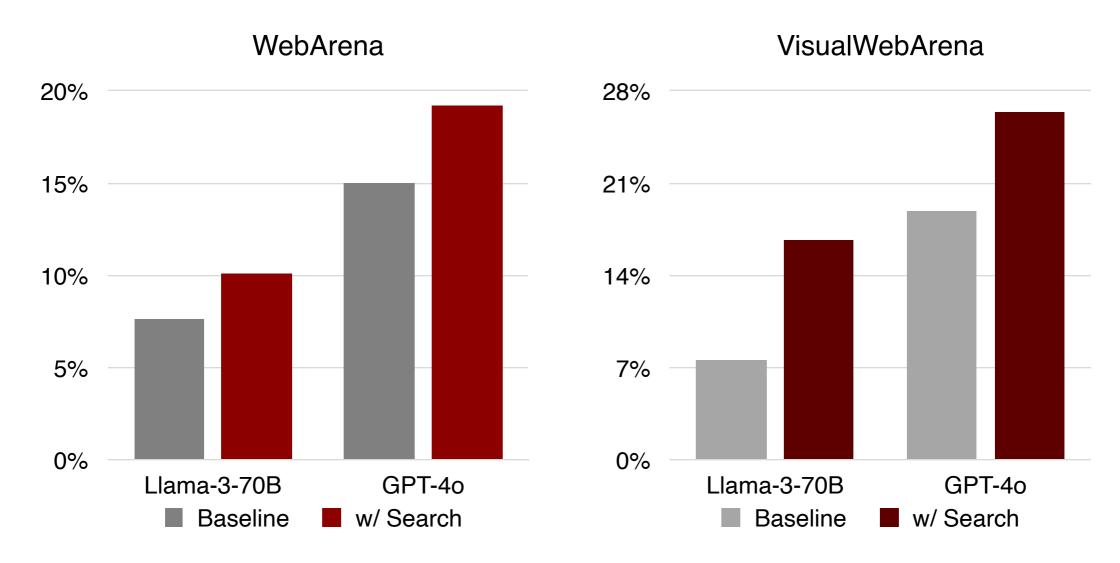




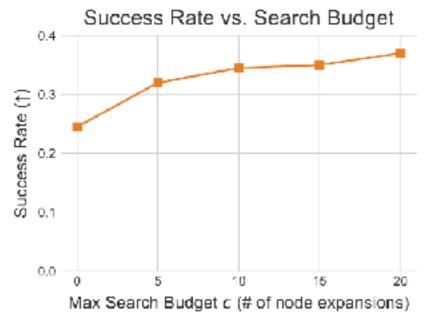




### Results



### **Ablations**



Success rate on a subset of 200 VWA tasks with search budget c. c = 0 indicates no search is performed. Success rate generally increases as c increases.

Depth d	Branch $b$	SR (↑)	Δ
0	1	24.5%	0%
1	3 5	26.0% 32.0%	+6% +31%
2	3 5	31.5% 35.0%	+29% +43%
3	5	35.5%	+45%
5	5	37.0%	+51%

Success rate (SR) and relative change over the baseline ( $\Delta$ ) on a subset of 200 VWA tasks with varying search depth (d) and branching factor (b). d=0 indicates no search is performed. All methods use a max search budget c=20.

### **Ablations**

- Having a good value function is essential.
- There is still a lot of headroom for improving both the base agent policy, and the value function.

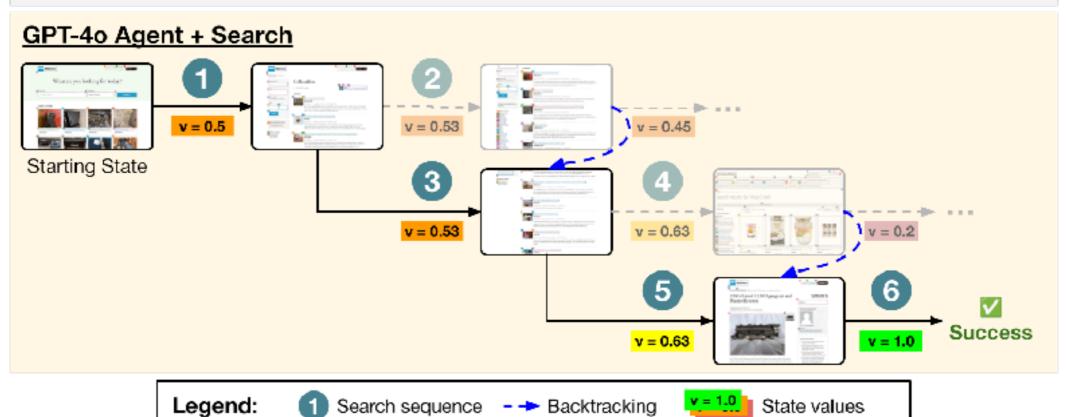
Value Function	<b>SR</b> (↑)
None (no search)	24.5%
LLaVA (w/ SC, $n = 20$ )	30.0%
GPT-4o (no SC)	28.5%
GPT-40 (w/ SC, $n = 5$ )	32.5%
GPT-40 (w/ SC, $n = 20$ )	37.0%

Table 3: Success rate of the GPT-40 agent with different value functions.

# **Qualitative Results**



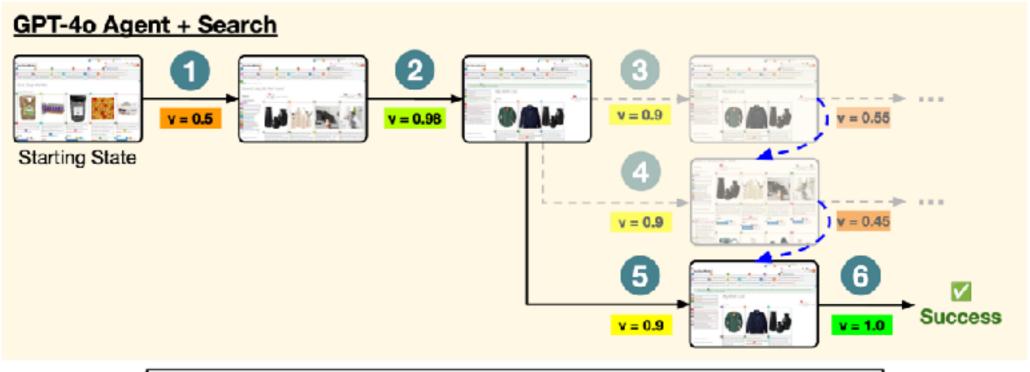
**Task Instruction** (I): "I recall seeing this exact item on the site, help me find the most recent post of it. I recall seeing it in either the Collectibles or Antiques section."



# **Qualitative Results**



**Task Instruction** (I): "I need something like this for my apartment. Can you add one to my wishlist?"



**Legend:** ① Search sequence -→ Backtracking V=1.0 State values

# Limitations

- Search is slow
  - We implemented backtracking in a relatively naive way (store actions in a queue, take them again to get to the original state)
- Dealing with destructive actions
  - Some things on the web are very difficult to undo, e.g., ordering an item

# **Current Work**

- Search as a policy improvement function
- Improving Value Function by fine-tuning instead of prompting
- Explore compute tradeoff between improving baseline agent vs.
   doing more search at inference time
- What if we don't have a perfect simulator how can we collect data at scale?

# Talk Outline

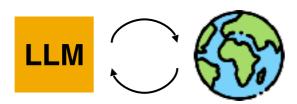
- VisualWebArena -- Evaluating Multimodal Agents on Realistic Visual Web Tasks (Koh et al., ACL 2024)
- Tree Search for Language Model Agents (Koh, McAleer, Fried, Salakhutdinov, arXiv 2024)
- Towards Internet-Scale Training For Agents (Trabucco, Sigurdsson, Piramuthu, Salakhutdinov, arXiv 2025)

# **Agents Suffer From A Data Problem**

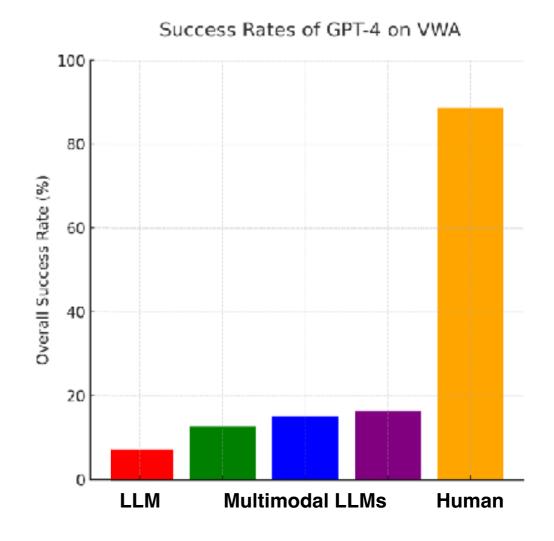
- Top LLMs fall short of humans by 68.92% on Visual Web Arena
- LLMs are often trained offline, then deployed zero-shot as agents



**Training Data** 

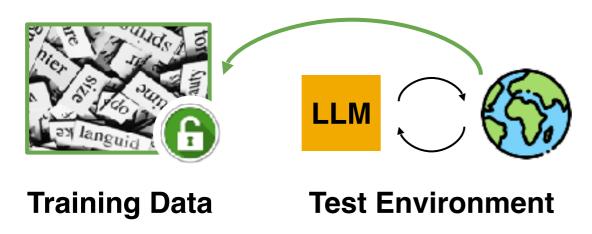


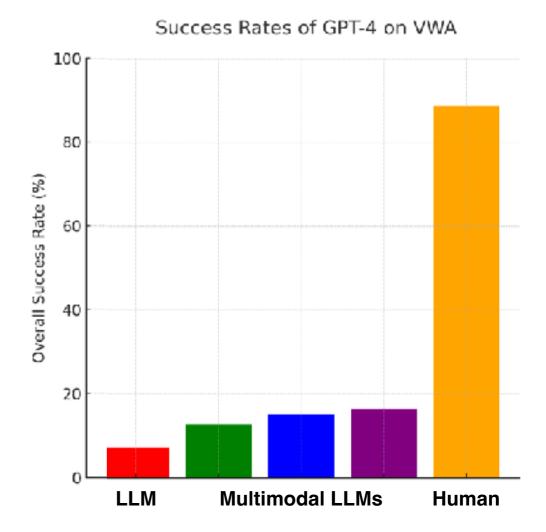
**Test Environment** 



# **Agents Suffer From A Data Problem**

- Top LLMs fall short of humans by 68.92% on Visual Web Arena
- Can synthetic tasks unlock internet-scale training for agents?





# Towards Internet-Scale Training For Agents (InSTA)

- Can synthetic tasks unlock internet-scale training for agents?
- Key Idea: use Llama to generate and verify synthetic agentic tasks

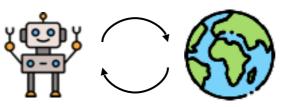


**Stage 1: Task Generation** 

**Stage 2: Task Evaluation** 

**Stage 3: Data Collection** 

www.github.com





Find a codebase for generating images with Flux.1 [dev].



Codebase found:



Task solved:



V

www.github.com
www.stackoverflow.com
www.uefi.org
www.jayatpoint.com
manuals.playstation.net
calculator.bcis.co.uk
research.vu.nl
...
(150k sites)

# Use Llama To Generate Agentic Tasks

- Given a web domain as text (i.e. merseyferries.co.uk)
- Propose a realistic task that an average user could complete in one session.

# Use Llama To Generate Agentic Tasks

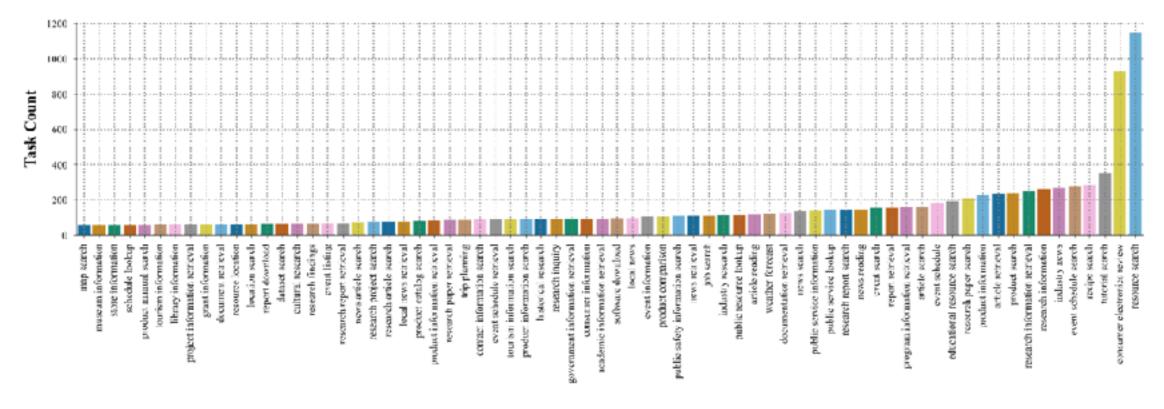
- Given a web domain as text (i.e. merseyferries.co.uk)
- Propose a realistic task that an average user could complete in one session.

## Llama-3.1-70B-Instruct: describe the "merseyferries.co.uk" site

Mersey Ferries (merseyferries.co.uk) is the **official website for the famous Mersey Ferry service** in Liverpool, England. This website serves as a one-stop platform for users to access various services and information related to the ferry operation. Here are some things a user can do on this site:

- 1. Plan a Journey: Users can plan their journey by checking the ferry timetable, which includes departure and arrival times for both commuter and cruise services.
- 2. Book Tickets: Users can book tickets online for both commuter and cruise services, including the popular Manchester Ship Canal Cruise and the Liverpool Bay Cruise.

# Use Llama To Generate Agentic Tasks



- Heavy-tailed distribution, most tasks involve information retrieval
- Crucially, tasks do not modify the state of the internet

 Tasks are diverse, and many require multiple steps of reasoning (i.e., what makes a font suitable for a children's book)

Web Domain	Generated Task
wordpress.org	Find a free and popular theme for a personal blog.
policies.google.com	Read Google's terms of service for using YouTube.
ec.europa.eu	Retrieve a report on the EU's climate change policy.
vimeo.com	Find a short film on environmental conservation.
fonts.adobe.com	Browse fonts suitable for a children's book.
apps.apple.com	Find the top-rated free productivity app for iPhone.

 Llama can identify facts that a site is likely to contain, such as the meaning of the Om symbol

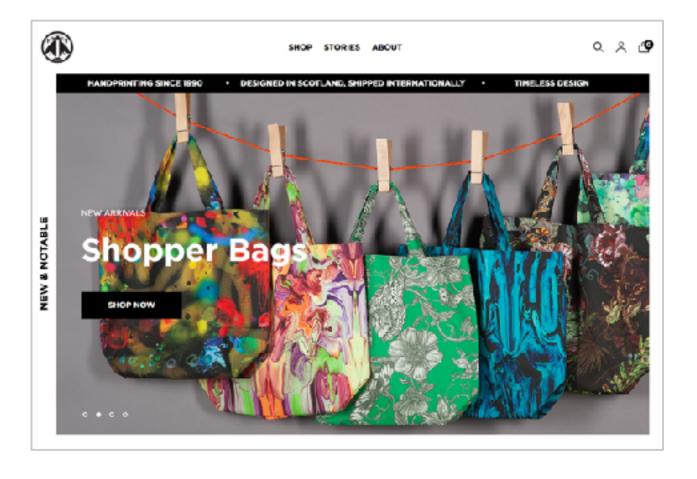
Web Domain	Generated Task
ancient-symbols.com	Look up the meaning of the Om symbol in ancient cultures.
petsforhomes.com.au	Find a list of available dogs for adoption in New South Wales.
timorousbeasties.com	View the latest fabric designs by the Timorous Beasties studio.
shop.nikon-image.com	Compare prices of the Nikon D850 and D500 cameras.
blueridgecountry.com	Find a scenic hiking trail in the Blue Ridge Mountains.
awg-fittings.com	Find the dimensions of a 1/2\" NPT fitting.

 Llama has broad knowledge of sites, such as for timorousbeasties.com, an independent Scottish design studio (fairly obscure)

Web Domain	Generated Task
ancient-symbols.com	Look up the meaning of the Om symbol in ancient cultures.
petsforhomes.com.au	Find a list of available dogs for adoption in New South Wales.
timorousbeasties.com	View the latest fabric designs by the Timorous Beasties studio.
shop.nikon-image.com	Compare prices of the Nikon D850 and D500 cameras.
blueridgecountry.com	Find a scenic hiking trail in the Blue Ridge Mountains.
awg-fittings.com	Find the dimensions of a 1/2\" NPT fitting.

View the latest fabric designs by the Timorous Beasties studio

 Tasks are grounded, even for sites in the tail of the data distribution



# The Data Pipeline

 Key Idea: use Llama to generate and verify synthetic agentic tasks.

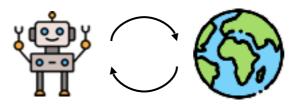


www.github.com



Find a codebase for generating images with Flux.1 [dev].

**Stage 2: Task Evaluation** 





Codebase found:



Task solved:



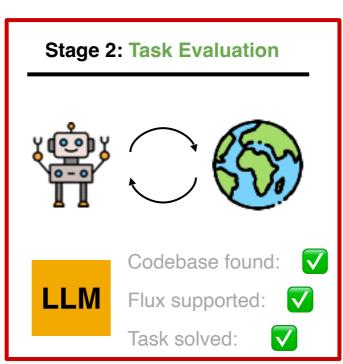
**Stage 3: Data Collection** 

www.github.com
www.stackoverflow.com
www.uefi.org
www.jayatpoint.com
manuals.playstation.net
calculator.bcis.co.uk
research.vu.nl
(150k sites)

# The Data Pipeline

- Key Idea: use Llama to generate and verify synthetic agentic tasks
- How do we know when tasks are solved? Build on Llama models





### **Stage 3: Data Collection**

www.github.com
www.stackoverflow.com
www.uefi.org
www.jayatpoint.com
manuals.playstation.net
calculator.bcis.co.uk
research.vu.nl
...
(150k sites)

# **Automatic Task Verification**

- How do we know when tasks are solved?
  - Observe a sequence of actions, and the last observation
  - Estimate the **probability the task is a success** at the final step

$$V_{\text{LLM}}(s_T, a_{1:T}) = P(\text{success}|s_T, a_{1:T})$$

# **Automatic Task Verification**

- How do we know when tasks are solved?
  - Observe a sequence of actions, and the last observation
  - Estimate the **probability the task is a success** at the final step

$$V_{\text{LLM}}(s_T, a_{1:T}) = P(\text{success}|s_T, a_{1:T})$$

- Prompt Llama to rate its confidence the task is solved on a scale from 0.0 (not possible) → 1.0 (certain)
- Of 150,000 tasks, 14.6% are rated as a success with a confidence of 1.0 by the Llama verifier, roughly 22,000 tasks

# **Proposed Task:** find invasive plant species native to North America

### Agent Response:

To find invasive plant species native to North America, I will first click on the link "All Species" to view the list of all species.





Non-native invasive species are organisms that have been introduced by humans either purposely or by addicent and that have become serious environmental pests. One reason for their success as pests is that they are typically introduced without the array of assectated natural centrols (herbitories, parasites, pathogens, predators) that occur in their native range. In addition to the great loss of bodiversity, habitat degradation and



Yaing Branes to Yrack Bangarous Envasive

Privet Biology and management in southeastern

### Agent Response:

To find invasive plant species native to North America, I will first click on the link "Home" to go back to the main page and then click on the link "Sources" to view the list of sources that provide information on invasive plant species native to North America.

However, since the link "Sources" is not on the current page, I will first click on the link "Home" to go back to the main page.

Here is the action in JSON format:

```
"action_key": "click",
    "action_kwargs": {},
    "target_element_id": 1
}
```

Misread Page



### Plant Species Reported to be Invasive in Natural Areas

The following species have been reported to be investive in natural areas in the U.S. Species native to the U.S. are included when they are invasive in areas well outside their known natural ranges, as a result of human activities. For more information on each species, including the listing sources, images, and distribution maps, click on the species.

### 1501 Records

Subject Name	Scientific Name 1	Num. of Counties	Habit
recarypea	Alires precatorius L.	54	Vines
hairy Indian mallov	Abusion grandilolium (willd.) sweet	6	Shain or Sulphrub
velvetical	Abution theophrasii Hedik	1340	Forbs/Herbs
earleaf acacla	Acardy acricolaforms A. Cusningham ex Senth.	21	Shain or Subshaib
codomundra wattle	Acania kalisyona F. Muell.	54	Hardwood Trees
small Philippine acada	Assolu conficta Herr	4	Hardwood Trop
cyclops acacia	Assov cyclops A. Curn. ex G. Den	5	Should on Subshould
silver wattle	Acade dealleta Link	32	Shab or Subshab
Syriney colden wartle	Acania Inngafelia (Andr.) Willd.	16	Hardword Tree
black wattle	Acacia meameli de Willdeman.	11	Hardwood Tree
black accola	Acada melanopion R. Br. exc.Nt. f.	36	Hardwood Tiron
kargarosthom	Aceda paredoxa DC.	9	Shoub or Substrub
golden valtle	Acada pytrantha Beeth.	6	Hardwood Trees
everbleoming seada	Assolu retinedes Schlecht.	12	Hardwood Trop

### Agent Response:

To find invasive plant species native to North America, I will first click on the link "Sources" to view the list of sources that provide information on invasive plant species native to North America.

```
Here is the action in JSON format:

``json
{
    "action_key": "click",
    "action_kwargs": {},
    "target_element_id": 15
}
```





Non-native invasive species are organisms that have been introduced by humans either purposely or by accident and that have become serious environmental pests. One reason for their success as pests is that they are typically introduced without the array of asseciated natural centrols (herbisones, parasites, pathogens, predators) that occur in their native range. In addition to the great loss of bodiversity, habitat degradation and



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### Agent Response:

- - -

To find invasive plant species native to North America, I will first click on the link "FONA" under the "Native Range and Taxonomic References" section, which stands for "Flora of North America". This will take me to the Flora of North America website, where I can search for invasive plant species native to North America.

```
Here is the action in JSON format:
    ``json
{
      "action_key": "click",
      "action_kwargs": {},
      "target_element_id": 25
```

```
Georgia Exetic Past Plant Council
Hoffman, R. & K., Kepme, Elds, 1997. Wicconsin manual of control recommendations for epologically invasive plants. Wicconsin Dept. Natural
Resources, Bureou of Endangered Resources, Madison, Wisconsin, 102cp.
III M. Swearingen, Survey of invasive plants occurring on National Fank Service lands, 2009 actual click (element 25)
3/ Swearingen, personal communication, 2009-2017.
John Randall, The Nature Conservency, Survey of TNC Preserves, 1995.
Kantucky Exotic Peet Plant Council
Maryland Concertive Extension Service, 2013, Invasive Plant Control in Harriand, Home and Gorden Information Center, Home and Gorden
Plimbe H338, 4 pg.
Native Plant Society of Oregon, 2008
New Hampshire Invasive Species Committee, 2005, Chide to Invasive Upland Plant Species in New Hampshire, New Hampshire Department.
of Agriculture. Markets and Food Plant Industry Division and New Hampshire Investive Species Committee.
Non-Native Invasive Plants of Arlington County, Virginia
Non-Native Invasive Plants of the City of Alexandria, Virginia
Obin Invasive Species Council.
Pacific Northwest Exotic Past Plant Council, 1998
Reichard, Serah. 1994. Assessing the potential of invasiveness in wordy plants introduced in North Emerica. University of Washington Pt. B.
dissectation
Rhedo Island Natural History Survey
South Deceins Exotic Post Plant Council
Tennessee Contic Pest Plant Council
Texas ) marine Database
Wirginia Brassive Plant Species List
Virginia Nocious weeds
Virginia Regulations for Enforcement of Novious Weeds Law
WeedUS - Detabase of Florits Inveding Natural Areas in the United States
West Virginia Native Plant Society, Flora West Virginia Project, and West Virginia Curstorial Database System, September 3, 1999.
```

### Native Range and Taxonomic References

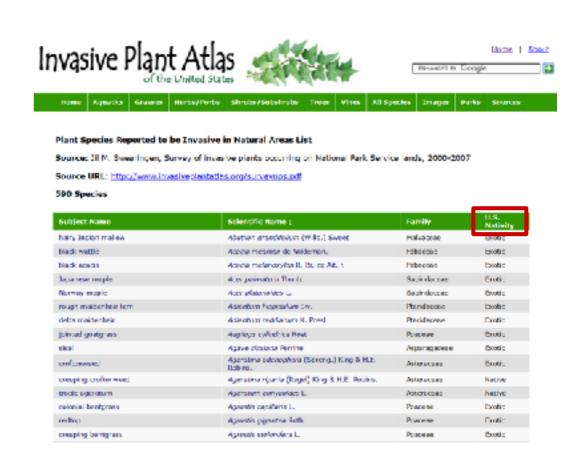
```
    Balle, Dailey, L.H. and E.Z. Bailey, Blottes Third. A Conside Cictionary of Plants California the United States and Conside, MacMillan Feld Many Co., Broy, New York., (1977).
    GRIN Agricultural Research Service, Germplacin Resources Information Network.
    HICK Hiddens, J.C., ed. 1993. The Jepson manual: Higher plants of California. Univ. California Press, Berveley, 1410 op.
    PANSE DI Nobberley. The Plant Bests A Portable Dictionary of the higher plants. Cambridge University Press, Cambridge, MA 1999.
    Hors of Rorth America.
    Kartesu, J.T. 1999. A synonymized checklist and attes with biological attributes for the vestorial Force of the Blotte States, Camerica, and Generaland. First edition. In: Partiest, I.T., and C.A. New Jean. Synthesis of the Blotth American Flora, Version 1.0. North Cambridge Broden, Chapel Hill, N.C.
    HAMS
    Menstell's world Castabase of Agricultural and Hamiltonius Long.
    REHD Africa Reflect: Pannel of Cultivated Trees and Shrubs: Hardy in North America (Bioclasive of the subtractical and warmer temperate regions). 2nd edition. 13th printing. The Hard Blan Co., New York (1967).
    RECS U.S. Department of Agricultura, Neutral Resources Conservation Service. Plants Debabase.
```

### Agent Response:

To find invasive plant species native to North America, I will first click on the link "Sort on "U.S. Nativity" to sort the list by the nativity of the plant species in the United States.

```
Here is the action in JSON format:

'`json
{
    "action_key": "click",
    "action_kwargs": {},
    "target_element_id": 20
}
```



### Agent Response:

To find invasive plant species native to North America, I will first scroll down the page to view the list of invasive plant species that are native to North America.

However, since the list is already sorted by "U.S. Nativity" in ascending order, I can see that the first 165 plant species are native to North America.

Here is the action in JSON format:

```
"json
{
    "action_key": "stop",
    "action_kwargs": {
        "answer": "The first 165 plant species on the
list are invasive plant species native to North
America."
    },
    "target_element_id": null
}
```



Solanum emencenom P. N.B.

Hobus arguitus Link

Rhynchospora cadves Ell.

Popular baltacellera L.

Plantago suscrafis Lam.

Plant settate D. Don

Pinne attrobus L.

Securia parellora (Peir.) Necualitar.

Prenciptures mession! (Mirtsell) france

Pluches carokhenski (Jeog.) C. Ben-

Piner ponderora R& C. Laveon

Provis pedforproview, is stall.

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Description.

Basaccae.

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Salicacase

Asteracese

Pinacase

Pinnerae

Pinacase

PROPERTY

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Netive

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Mative

Markw

Mative

Native

Amorroan black mohtshado

landress feetail

Daughe-Sir

cure for all

beleam poplar

Mexican plantain

Montgrey pine

ponderosa pine

settiney pune

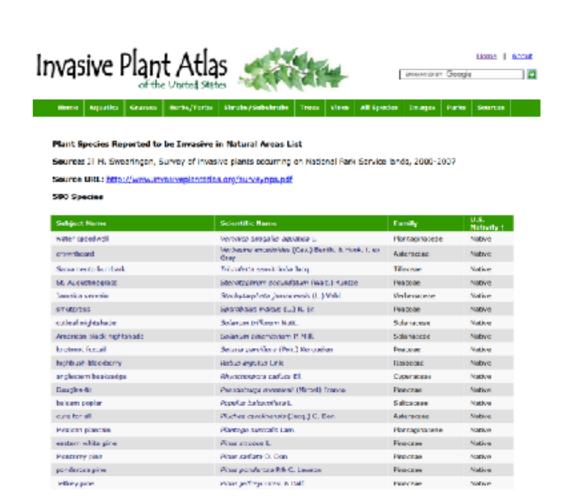
eastern white pine

highbush bloodscriy

anglessem beakssége

**Proposed Task:** find invasive plant species native to North America

- Despite reasoning failures, the agent self-corrected, and found the target information
- The Llama verifier evaluates this trajectory as successful with confidence = 1.0



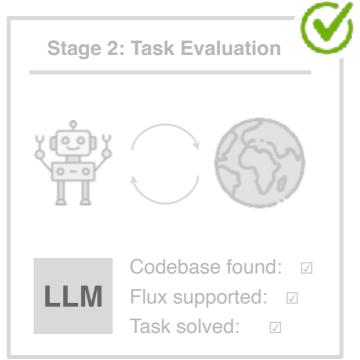
# Find the opening hours for La Sagrada Familia.

# Find information on the European Union's climate action policies.

# The Data Pipeline

 We've covered generation and verification of synthetic agentic tasks





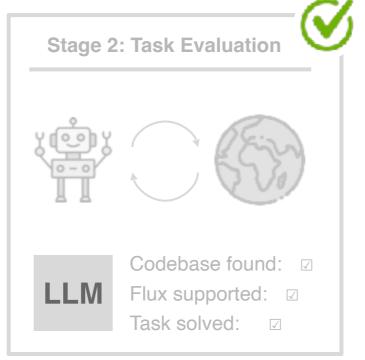
### **Stage 3: Data Collection**

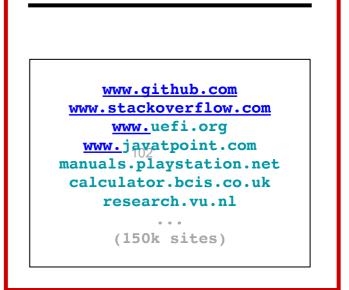
www.github.com
www.stackoverflow.com
www.uefi.org
www.javatpoint.com
manuals.playstation.net
calculator.bcis.co.uk
research.vu.nl
...
(150k sites)

# The Data Pipeline

- We've covered generation and verification of synthetic agentic tasks
- Now we can scale up data collection



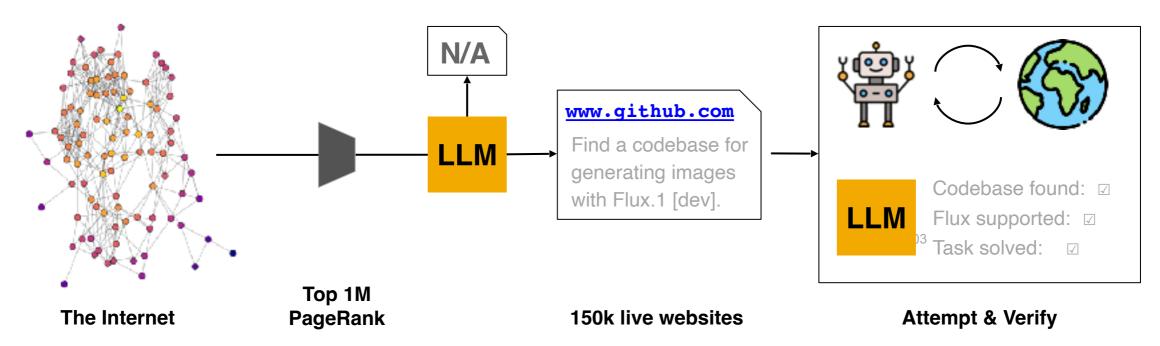




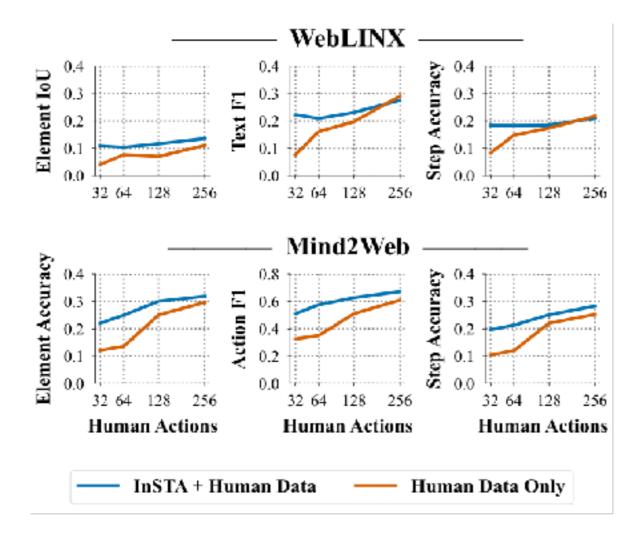
**Stage 3: Data Collection** 

# Scaling Up To 150k Live Websites

- We can use the Common Crawl PageRank to find important sites
  - 97% accuracy in detecting and filtering harmful content
  - **89% success rate** in generating feasible tasks
  - 82% accuracy in judging successful task completions

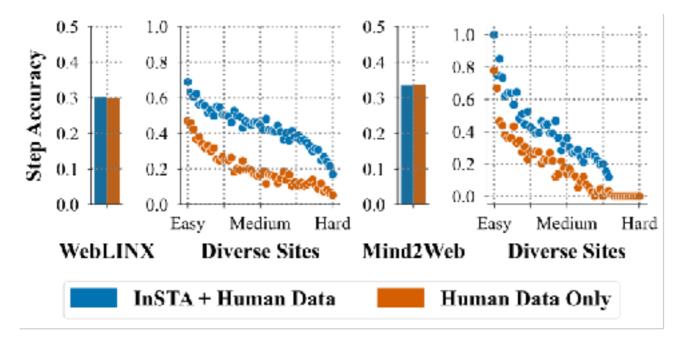


# Results: Improving Efficiency



- Training on synthetic and human demonstrations scale faster than training on human data
- Adding synthetic data improves
   Step Accuracy by
  - +89.5% relative to human data for Mind2Web
  - +122.1% relative to human data for WebLINX

# Results: Improving Generalization



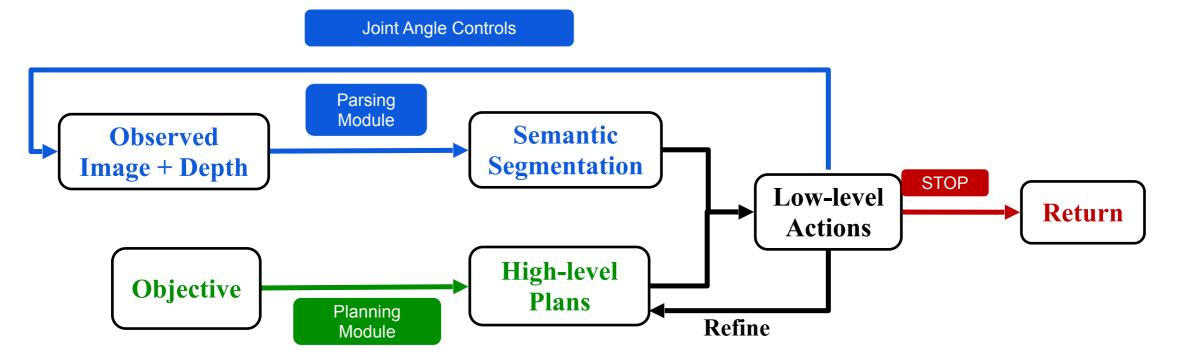
- Training with only human demonstrations struggle with generalization
- Adding synthetic data improves generalization by
  - +149.0% for WebLINX
  - +156.3% for Mind2Web

# **Next Steps**

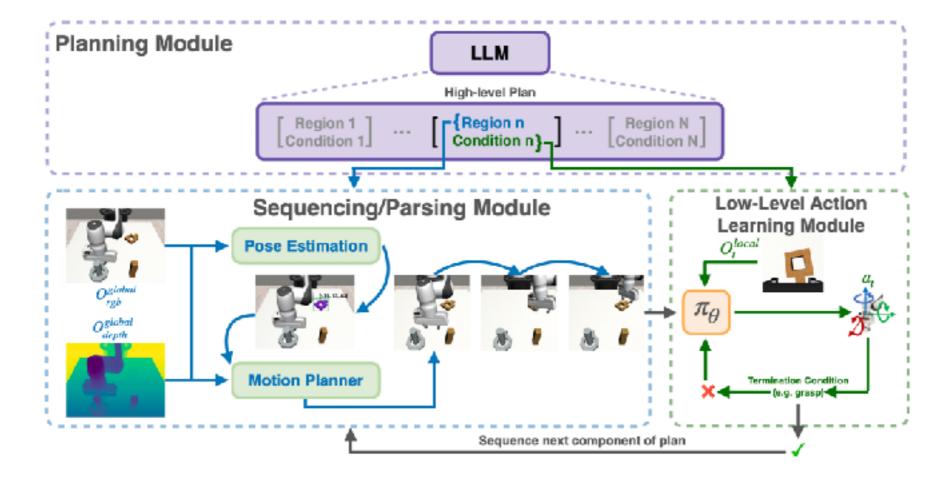
- There are 385M unique domains in the Common Crawl PageRank, suggesting another 1000x more data could be available by scaling further
- Moving towards online RL

# Physical Agent: Long-horizon Robotic Manipulation Task

- Model architecture of our interactive agent:
  - High-level Planning
  - Observation Parsing
  - Low-level Action Generation



# Plan-Sequence-Learn





Murtaza Dalal

Plan-Seq-Learn (PSL): Language Model Guided RL for Solving Long Horizon Robotics, M Dalal, T Chiruvolu, D Chaplot, R Salakhutdinov, ICLR 2024

# Planning Module

- Structured language plans: (object, condition)
- Prompt: Task description, conditions, objects, formatting

Stage termination conditions: (grasp, place).

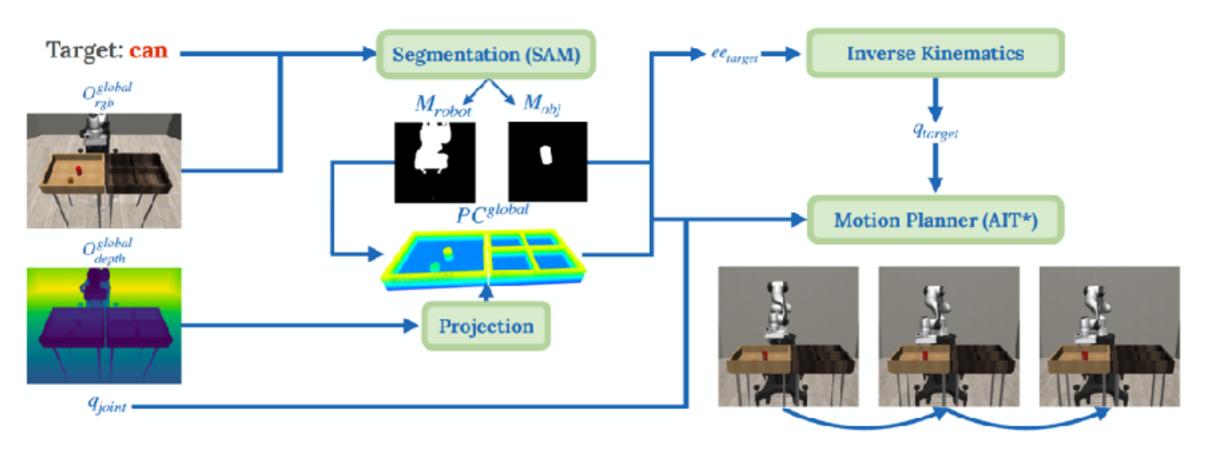
**Task description**: The silver nut goes on the silver peg and the gold nut goes on the gold peg. Give me a simple plan to solve the task using only the stage termination conditions. Make sure the plan follows the formatting specified below and make sure to take into account object geometry.

**Formatting of output**: a list in which each element looks like: (<object/region>, <stage termination condition>). Don't output anything else.

#### **Output:**

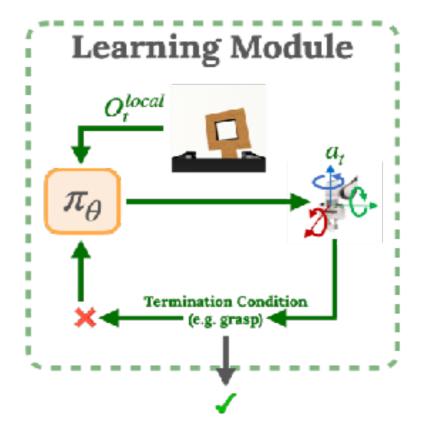
```
[("silver nut", "grasp"), ("silver peg", "place"), ("gold nut", "grasp"), ("gold peg", "place")]
```

### Sequencing/Parsing Module: Grounding Language Plans in the Scene



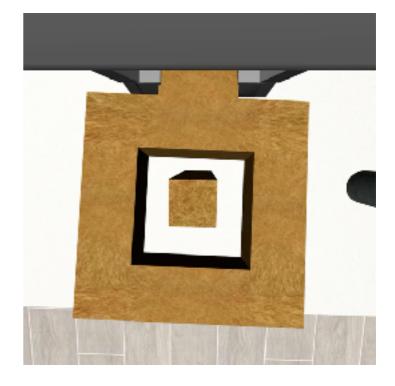
### Learning Low-level Actions Module: Learning Local Control

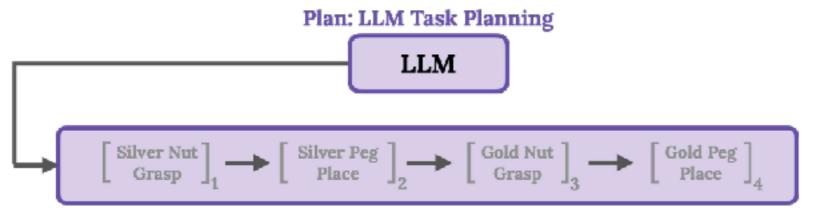
- Learned RL policies for interaction
- Trained with task reward
- Single RL model instead of separate per stage
- Local instead of global observations

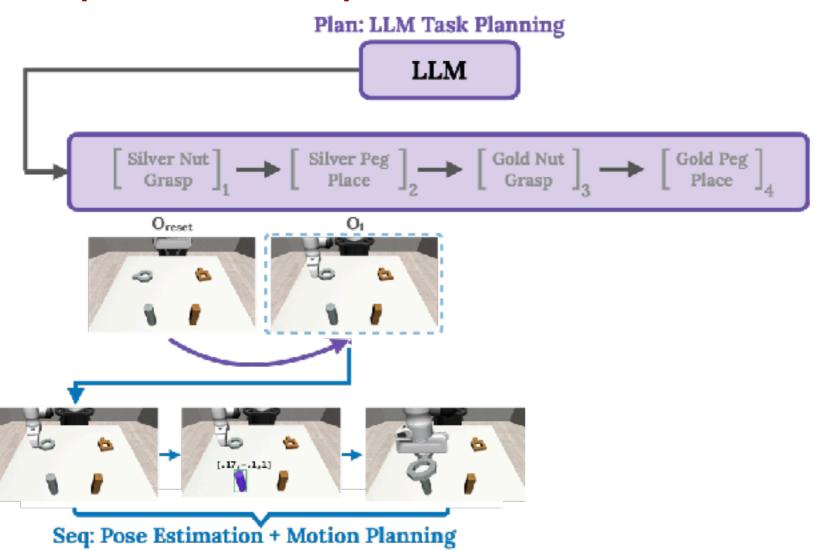


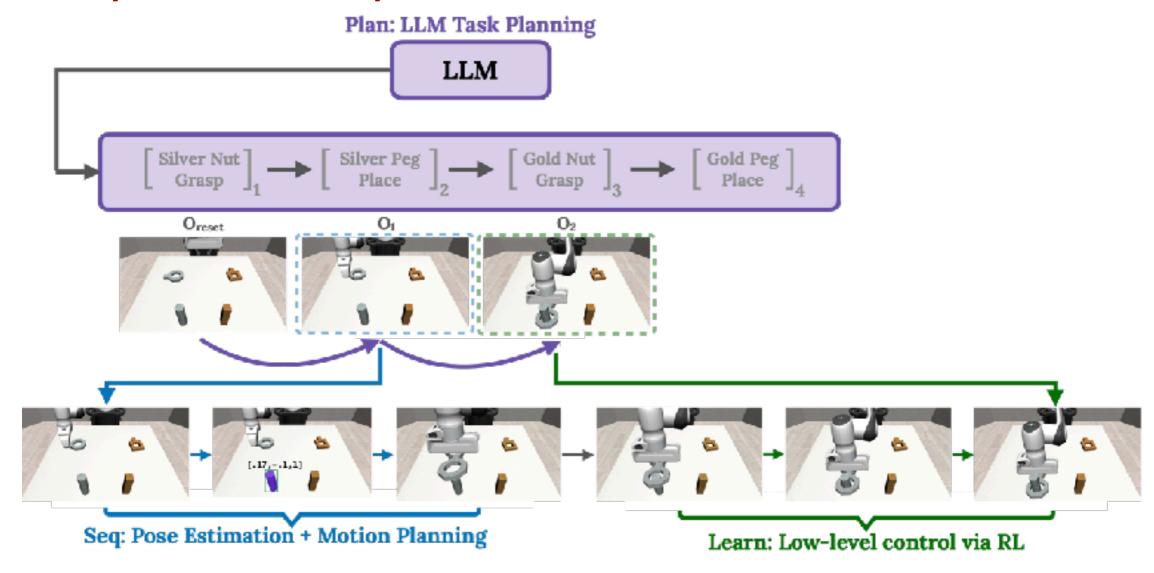
## Learning Low-level Actions Module: Learning Local Control

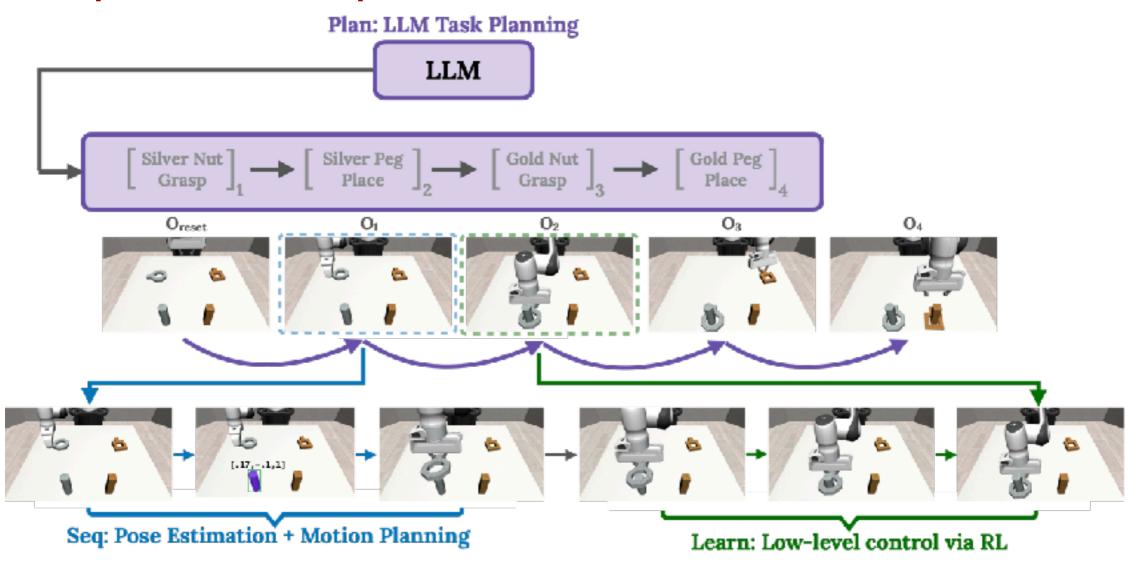
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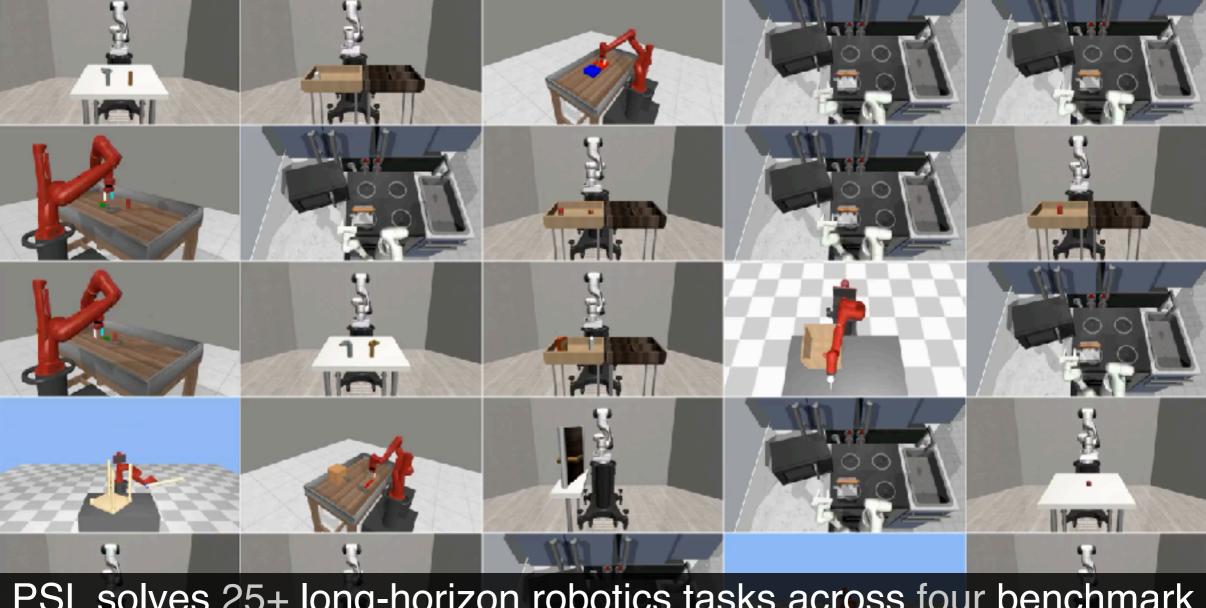




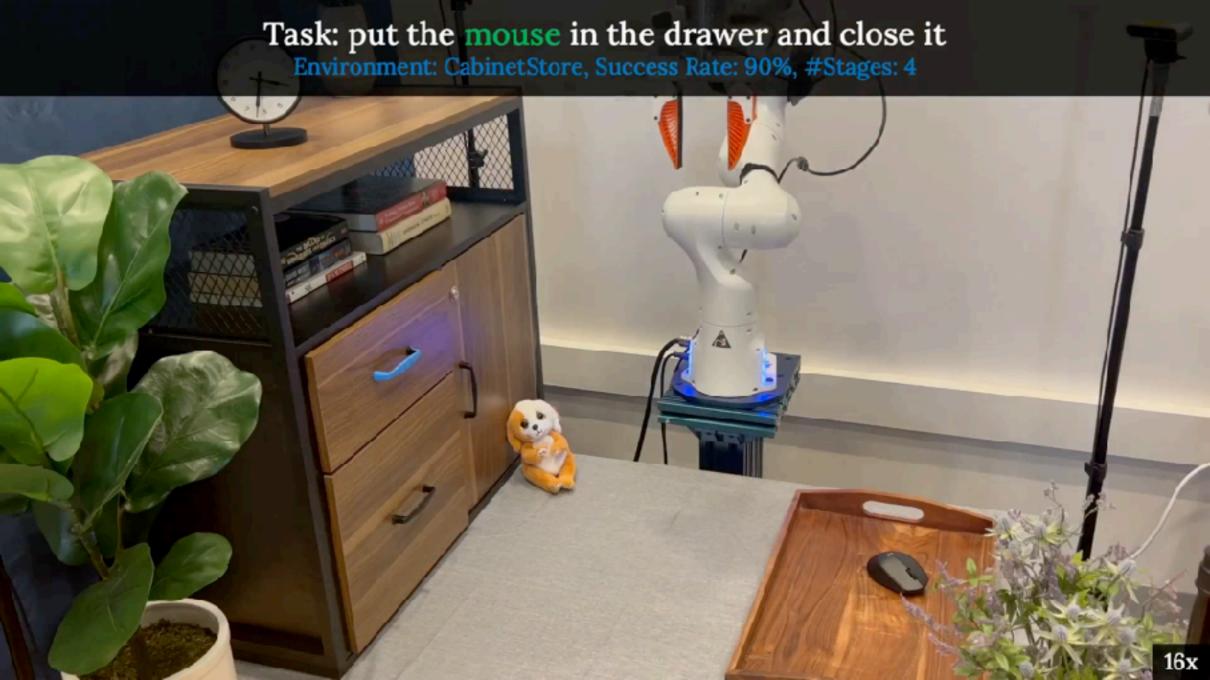








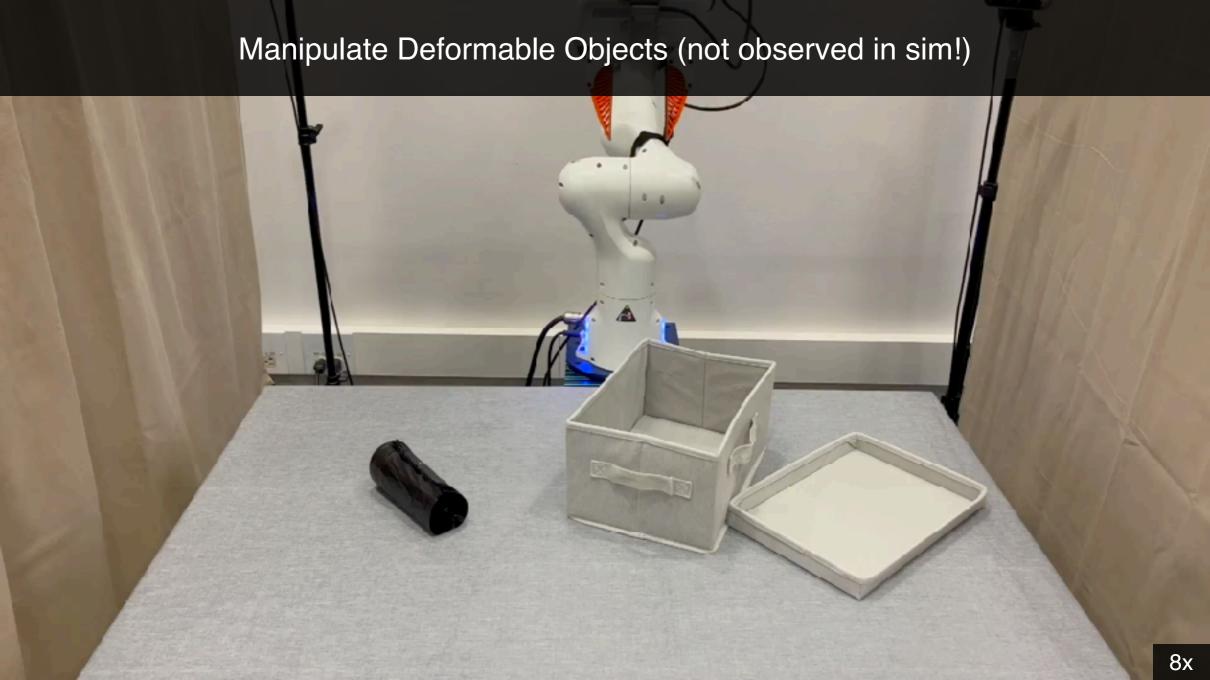
PSL solves 25+ long-horizon robotics tasks across four benchmark environment suites with greater than 85% success rates



#### Generalizes to Novel Object Geometries/Categories







### Summary

- VisualWebArena: a benchmark of realistic tasks designed to rigorously evaluate and advance the capabilities of autonomous multimodal web agents
- Inference-time search algorithm designed to enhance the capabilities of language model agents on realistic web tasks
- Data pipeline for large-scale generation and verification of synthetic web tasks, powered by Llama models

### Summary

- VisualWebArena: a benchmark of realistic tasks designed to rigorously evaluate and advance the capabilities of autonomous multimodal web agents
- Inference-time search algorithm designed to enhance the capabilities of language model agents on realistic web tasks
- Data pipeline for large-scale generation and verification of synthetic web tasks, powered by Llama models
- Al Safety and robustness, especially in the age of autonomous systems.

#### Adversarial Attacks on Multimodal Agents

Chen Henry Wu, Jing Yu Koh, Ruslan Salakhutdinov, Daniel Fried, Aditi Raghunathan
Carnegie Mellon University
{chenwu2, jingyuk, rsalakhu, dfried, aditirag}@cs.cmu.edu



Even while we were recording demonstrations of computer use for today's launch, we encountered some amusing errors. In one, Claude accidentally clicked to stop a long-running screen recording, causing all footage to be lost. In another, Claude suddenly took a break from our coding demo and began to peruse photos of Yellowstone National Park.

We expect that computer use will rapidly improve to become faster, more reliable, and more useful for the tasks our users want to complete. It'll also become much easier to implement for those with less software-development experience. At every stage, our researchers will be working closely with our safety teams to ensure that Claude's new capabilities are accompanied by the appropriate safety measures.

# Thank you